

SKELETA OF AFFINE HYPERSURFACES

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ABSTRACT. A smooth affine hypersurface Z of complex dimension n is homotopy equivalent to an n -dimensional cell complex. Given a defining polynomial f for Z as well as a regular triangulation \mathcal{T}_Δ of its Newton polytope Δ , we provide a purely combinatorial construction of a compact topological space S as a union of components of real dimension n , and prove that S embeds into Z as a deformation retract. In particular, Z is homotopy equivalent to S .

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1. INTRODUCTION

The Lefschetz hyperplane theorem is equivalent to the assertion that a smooth affine variety Z of complex dimension n has vanishing homology in degrees greater than n . A stronger version of this assertion is attributed in the work of Andreotti-Frankel [AF] to Thom: Z actually deformation retracts onto a cell complex of real dimension at most n . We will borrow terminology from symplectic geometry and call a deformation retract with this property a *skeleton* for Z . The purpose of this paper is to investigate the combinatorics of such skeleta for affine hypersurfaces $Z \subseteq \mathbb{C}^{n+1}$, and a more general class of affine hypersurfaces in affine toric varieties. In particular, we give a combinatorial recipe for a large number of skeleta for any given such hypersurface.

By “combinatorial” we mean that our skeleton makes contact with standard discrete structures from algebraic combinatorics, such as polytopes and partially ordered sets. Before explaining what we mean in more detail, let us recall for contrast Thom’s beautiful Morse-theoretic proof of Lefschetz’s theorem, which provides a recipe of a different nature. Fix an embedding $Z \subseteq \mathbb{C}^N$, and let $\rho : Z \rightarrow \mathbb{R}$ be the function that measures the distance to a fixed point $P \in \mathbb{C}^N$. For a generic choice of P , this is a Morse function, and since it is harmonic, its critical points cannot have index larger than n . Thom’s skeleton is the union of stable manifolds for the gradient flow of ρ .

This recipe reveals many important things about the skeleton (most important among them that the skeleton is *Lagrangian*, a point that has motivated us but plays no role in this paper). The proof also works in the more general context of Stein and Weinstein manifolds, see e.g.

[CE]. However, finding an explicit description of these stable manifolds requires one to solve some fairly formidable differential equations. In this paper, we avoid this difficulty by defining a skeleton through a simple, combinatorial construction.

One might expect a rich combinatorial structure to emerge from the theory of Newton polytopes for hypersurfaces. The situation is simplest for hypersurfaces in $(\mathbb{C}^*)^{n+1}$ rather than in \mathbb{C}^{n+1} —we will explain this special case here, and the general situation in Section 5. If Z is a hypersurface in $(\mathbb{C}^*)^{n+1}$ we can write its defining equation as $f = 0$, where f is a Laurent polynomial of the form

$$\sum_{m \in \mathbb{Z}^{n+1}} a_m z^m.$$

Here, if we write m as (m_1, \dots, m_{n+1}) and the coordinates on $(\mathbb{C}^*)^{n+1}$ as z_1, \dots, z_{n+1} , then z^m denotes the monomial $z_1^{m_1} \cdots z_{n+1}^{m_{n+1}}$. The convex hull of the set of m for which the coefficient a_m is nonzero is called the *Newton polytope* of f . By multiplying f by a monomial, we may assume without loss of generality that the Newton polytope contains 0. The significance of this definition is that, for a generic choice of coefficients a_m , the topological type of the hypersurface depends only on this polytope. From this point of view, one goal might be to construct a combinatorial skeleton which also depends only on this polytope. Actually, we need a triangulation too. This should not be surprising: a skeleton is not unique, as different Morse functions will produce different skeleta. Our combinatorial version of a Morse function turns out to be a triangulation: different triangulations will produce different skeleta.

Definition 1.1. Let $\Delta \subseteq \mathbb{R}^{n+1}$ be a lattice polytope with $0 \in \Delta$. Let \mathcal{T}_Δ be a star triangulation of Δ based at 0, and define \mathcal{T} to be the set of simplices of \mathcal{T}_Δ not meeting 0. Write $\partial\Delta'$ for the support of \mathcal{T} . (Note $\partial\Delta'$ equals the boundary $\partial\Delta$ if 0 is an interior point. Note, too, that \mathcal{T} determines \mathcal{T}_Δ , even if $0 \in \partial\Delta$.) Define $S_{\Delta, \mathcal{T}} \subseteq \partial\Delta' \times \text{Hom}(\mathbb{Z}^{n+1}, S^1)$ to be the set of pairs (x, ϕ) satisfying the following condition:

$$\phi(v) = 1 \text{ whenever } v \text{ is a vertex of the smallest simplex } \tau \in \mathcal{T} \text{ containing } x$$

Put $S := S_{\Delta, \mathcal{T}}$. Then we have:

Theorem 1.2 (Main Theorem). *Let Δ and \mathcal{T} be as in Definition 1.1. Let Z be a generic hypersurface whose Newton polytope is Δ . If \mathcal{T} is regular, then S embeds into Z as a deformation retract.*

The term “regular” is explained in Section 2. We do not know if this hypothesis can be removed but note that every lattice polytope admits a regular lattice triangulation. The role the triangulation plays in the proof is in the construction of a degeneration of Z . Regularity of the triangulation allows the projection $(x, \phi) \mapsto x$ of S to $\partial\Delta$ (or to the support of \mathcal{T} if 0 is on the boundary of Δ) to be identified with the specialization map, under which the skeleton of Z projects to a kind of nonnegative locus of toric components. For more see Section 1.1 below.

Generalization. In Section 5, we prove the extension of our theorem to the case where Z is a smooth affine hypersurface in a more general affine toric variety, such as \mathbb{C}^{n+1} , $(\mathbb{C}^*)^k \times \mathbb{C}^l$, or even singular spaces such as $\mathbb{C}^2/\mathbb{Z}_2$. In these cases, we define the skeleton as a quotient of the construction of Definition 1.1.

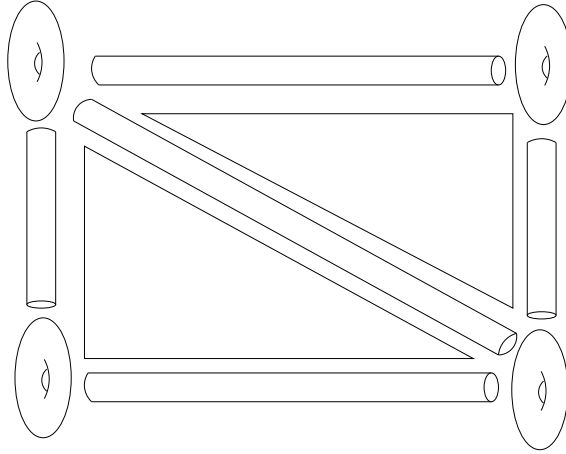


FIGURE 1. The tetrahedron $\Delta \subseteq \mathbb{R}^3$ with vertices at $(1, 0, 0)$, $(0, 1, 0)$, $(0, 0, 1)$, and $(-1, -1, -1)$ has a unique lattice triangulation \mathcal{T} . The figure shows part of $S_{\Delta, \mathcal{T}}$, which by Theorem 1.2 is a skeleton of a surface in $\mathbb{C}^* \times \mathbb{C}^* \times \mathbb{C}^*$ cut out by the quartic equation $Ax + By + Cz + \frac{D}{xyz} + E = 0$. Each “tube” is attached to a torus along a different circle in $S^1 \times S^1$, and the resulting figure does not embed in \mathbb{R}^3 . There is a sixth tube and two additional triangles “behind” the diagram, they are to be glued together in the shape of the tetrahedron Δ .

1.1. Log geometry and the proof. The technique of the proof is to use the triangulation to construct a degeneration of the ambient $(\mathbb{C}^*)^{n+1}$, and with it the hypersurface. The components of the degeneration are affine spaces along which the hypersurface has a simple description: it is an affine Fermat hypersurface, and a finite branched cover over affine space (see also the discussion of Mikhalkin’s work in Section 1.2). So the degenerated hypersurface is well understood.

Example 1.3. Consider the space $Z = \{-1 + x + y + x^{-1}y^{-1} = 0\}$ inside $\mathbb{C}^* \times \mathbb{C}^*$, topologically a two-torus with three points removed. The Newton polytope $\Delta = \text{conv}\{(1, 0), (0, 1), (-1, -1)\} \subseteq \mathbb{R}^2$ has a unique regular triangulation corresponding to the unique lattice triangulation of its boundary. To understand the associated degeneration, first identify $\mathbb{C}^* \times \mathbb{C}^*$ with the locus $\{abc = 1\} \subseteq \mathbb{C}^3$ and describe Z by the equation $-1 + a + b + c = 0$. Next we can identify this geometry with the locus $t = 1$ inside the family $\{abc = t^3\} \subseteq \mathbb{C}^4$. At $t = 0$, we have for the ambient space $\mathbb{C}_{\{a=0\}}^2 \cup \mathbb{C}_{\{b=0\}}^2 \cup \mathbb{C}_{\{c=0\}}^2$, with the hypersurface described by $\{b + c = 1\} \cup \{c + a = 1\} \cup \{a + b = 1\}$, i.e. a union of affine lines.

Up to the action of a discrete group, the degenerated hypersurface retracts to a simpler locus: the union of *nonnegative loci* of the components. (In the example above, the complex line $\{a + b = 1\} \subseteq \mathbb{C}_{\{c=0\}}^2$ retracts to the real interval $\{a + b = 1, a \geq 0, b \geq 0\}$.) What remains is to account for the topological distinction between the degenerated hypersurface and the general one. Log geometry provides the answer, and the toric setting is particularly simple. A toric variety comes with a standard log structure which can be pulled back to a toric stratum, enabling the stratum to “remember” how it is embedded in the ambient space. In short, the compact torus fixing the defining equations of a stratum of the degeneration serves as the

exceptional torus in a real, oriented blow-up from which one can extract the nearby fiber of the degenerate hypersurface.

Example 1.4. To illustrate this point, consider first the local geometry of the degeneration near a singular point of Example 1.3, i.e. $\{uv = \epsilon^2\} \subseteq \mathbb{C}^2$. The two-torus $S^1 \times S^1 \subseteq \mathbb{C}^* \times \mathbb{C}^*$ acts on \mathbb{C}^2 and the “antidiagonal” circle fixes the defining equation for all ϵ . That we want to “keep” this circle is clear once we describe the locus $\{uv = \epsilon^2\}$ by gluing the boundary circles of $\{|u| \geq |\epsilon|\} \subseteq \mathbb{C}$ to $\{|v| \geq |\epsilon|\} \subseteq \mathbb{C}$ – the antidiagonal circle acts transitively on the exceptional circle which vanishes as $\epsilon \rightarrow 0$. Combinatorially, this circle is the Lie group generated by the annihilator of the vector $(1, 1)$ of exponents in the expression uv . In our example, the degeneration happens in three dimensions, but the relevant circles can be related to two-dimensional circles generated by annihilators $(1, 0)^\perp$, $(0, 1)^\perp$, $(-1, -1)^\perp$ of the two-dimensional vectors of exponents. The skeleton of Z , a torus with three points removed, is thus described as a triangle with circles attached to its vertices.

1.2. Related Work. Algebraic hypersurfaces in complex tori have been studied by Danilov-Khovanskii [DK] and Batyrev [Ba93]. Danilov-Khovanskii computed mixed Hodge numbers, while Batyrev studied the variation of mixed Hodge structures. Log geometry has been extensively employed by Gross and Siebert [GS] in their seminal work studying the degenerations appearing in mirror symmetry. Their strategy is crucial to our work, even though we take a somewhat different track by working in a non-compact setting for hypersurfaces that are not necessarily Calabi-Yau. The non-compactness allows us to deal with log-smooth log structures. Mirror symmetry for general hypersurfaces was recently studied in [GKR] (projective case) and [AAK] (affine case) using polyhedral decompositions of the Newton polytope. This relates to the Gross-Siebert program by embedding the hypersurface in codimension two in the special fiber of a degenerating Calabi-Yau family. In this family, the hypersurface coincides with the log singular locus — see [R] for the simplicial case.

In the symplectic-topological setting, Mikhalkin [M] constructed a degeneration of an algebraic hypersurface using a triangulation of its Newton polytope to provide a higher-dimensional “pair-of-pants” decomposition. He further identified a stratified torus fibration over the spine of the corresponding amoeba. This viewpoint was first applied to homological mirror symmetry (“HMS”) by Abouzaid [A]. Mikhalkin’s construction and perspective inform the current work greatly, even though our route from HMS is a bit “top-down.” We describe it here.

When Δ is reflexive, Z can be seen as the “large volume limit” of a family of Calabi-Yau hypersurfaces in the toric variety \mathbb{P}_Δ defined by Δ . The dual polytope Δ^\vee corresponds to the toric variety \mathbb{P}_{Δ^\vee} containing the mirror family. The mirror “large complex limit” Z^\vee is the union of reduced toric divisors of \mathbb{P}_{Δ^\vee} . In [FLTZ] a relation was found between coherent sheaves on a toric variety, such as \mathbb{P}_{Δ^\vee} , and a subcategory of constructible sheaves on a real torus. The subcategory is defined by a conical Lagrangian Λ in the cotangent bundle of the torus. As discussed in [TZ], specializing to Z^\vee , the complement of the open orbit of \mathbb{P}_Δ , can be achieved by excising the zero section from Λ . The resulting conical Lagrangian is homotopy equivalent to the Legendrian Λ^∞ at contact infinity of the cotangent. We can now explain how this relates to skeleta. First, when Δ is reflexive and simplicial and we choose \mathcal{T} to be the canonical triangulation of its boundary, then S is homomorphic to Λ^∞ . In [TZ] it is shown that Λ^∞ supports a Kashiwara-Schapira sheaf of dg categories, and this is equivalent to the “constructible plumbing model” of [STZ]. Following [STZ], this sheaf should

be equivalent to perfect complexes on Z^\vee and it is conjectured in [TZ] that under homological mirror symmetry it is also equivalent to the sheaf of Fukaya categories, conjectured to exist by Kontsevich, supported on the skeleton of Z . In particular, S should be the skeleton of Z itself, and in the simplicial reflexive case this was conjectured in [TZ].

1.3. Notation and conventions.

1.3.1. Hypersurfaces in an algebraic torus. Each $(m_0, \dots, m_n) \in \mathbb{Z}^{n+1}$ determines a monomial function $(\mathbb{C}^*)^{n+1} \rightarrow \mathbb{C}$ which we denote by $z^m = \prod_{i=0}^n z_i^{m_i}$. If $f : (\mathbb{C}^*)^{n+1} \rightarrow \mathbb{C}$ is a Laurent polynomial we let $V(f) = \{z \mid f(z) = 0\}$ denote its zero locus. The *Newton polytope* of f is the convex hull of the set of $m \in \mathbb{Z}^{n+1}$ whose coefficient in f is nonzero. If the coefficients are chosen generically, then the diffeomorphism type of $V(f)$ depends only on the Newton polytope of f . In fact it suffices that the extreme coefficients (i.e. the coefficients corresponding to the vertices of the Newton polytope) are chosen generically. More precisely,

Proposition 1.5 (e.g. [GKZ, Ch. 10, Cor. 1.7]). *Let $A \subseteq \mathbb{Z}^{n+1}$ be a finite set whose affine span is all of \mathbb{Z}^{n+1} , and let f_A be a Laurent polynomial of the form*

$$f(z) = \sum_{m \in A} a_m z^m$$

There is a Zariski dense open subset $U_A \subseteq \mathbb{C}^{|A|}$ such that, when the $(a_m)_{m \in A}$ are chosen from U_A , the variety $V(f_A)$ is smooth and its diffeomorphism type depends only on the convex hull of A .

1.3.2. Polytopes and triangulations. An intersection of finitely many affine half-spaces in a finite-dimensional vector space is called *polyhedron*. If it is compact, it is called *polytope*. A polytope is the convex hull of its vertices. Given a subset A of a vector space, we denote its convex hull by $\text{conv} A$. Throughout, we let M denote a free abelian group isomorphic to \mathbb{Z}^{n+1} and set $M_{\mathbb{R}} = M \otimes_{\mathbb{Z}} \mathbb{R} \cong \mathbb{R}^{n+1}$. A polytope $\Delta \subseteq M_{\mathbb{R}}$ is called a *lattice polytope* if its vertices are in M . We use the symbol \subseteq for the face relation, e.g., $\tau \subseteq \Delta$ means that τ is a face of Δ . The relative interior of a polytope τ will be denoted τ° . Let $\partial\Delta$ denote the boundary of Δ . A lattice triangulation \mathcal{T}_Δ of a polytope Δ is a triangulation by lattice simplices. Such a triangulation is called *regular* if there is a piecewise affine function convex function $h : \Delta \rightarrow \mathbb{R}$ such that the non-extendable closed domains where h is affine linear coincide with the maximal simplices in \mathcal{T}_Δ . We write $\mathcal{T}_\Delta^{[0]}$ for the set of vertices of \mathcal{T}_Δ , and if τ is a simplex of \mathcal{T}_Δ we write $\tau^{[0]}$ for the vertices of τ .

1.3.3. Monoids and affine toric varieties. We denote by $\text{Spec } R$ the spectrum of a commutative ring R . When R is a noetherian commutative algebra over \mathbb{C} , we will often abuse notation and use the same symbol $\text{Spec } R$ for the associated complex analytic space. Given $f_1, \dots, f_r \in R$, we write $V(f_1, \dots, f_r)$ for the subvariety of $\text{Spec } R$ defined by the equations $f_1 = \dots = f_r = 0$.

A *monoid* is a set with an associative unit and a two-sided identity. For us, all monoids will be commutative. Given a monoid \mathbf{M} with an action on a set V , we write $\mathbf{M}T$ for the orbit of a subset $T \subseteq V$. We often use this when V is an \mathbb{R} -vector space, T some subset and $\mathbf{M} = \mathbb{R}_{\geq 0}$ the non-negative reals. See also Section 4.1.

By a *cone* $\sigma \subseteq M_{\mathbb{R}}$ we shall always mean a rational polyhedral cone, i.e. a set of the form

$$\left\{ \sum_{i \in I} \lambda_i v_i \mid \lambda_i \in \mathbb{R}_{\geq 0} \right\}$$

where $\{v_i\}_{i \in I}$ is a finite subset of lattice vectors in $M_{\mathbb{R}}$. A cone is called *strictly convex* if it contains no nonzero linear subspace of $M_{\mathbb{R}}$. Gordon's Lemma [Fu, p. 12] states that the monoid $M \cap \sigma$ is finitely generated. The monoid ring $\mathbb{C}[M \cap \sigma]$ is then noetherian. For $m \in M \cap \sigma$ we write z^m for the corresponding basis element of $\mathbb{C}[M \cap \sigma]$; it can be regarded as a *regular monomial* function $\text{Spec } \mathbb{C}[M \cap \sigma] \rightarrow \mathbb{C}$.

We have the following standard device for describing points on an affine toric variety. If x is a point of $\text{Spec } \mathbb{C}[M \cap \sigma]$, write $\text{ev}_x : M \cap \sigma \rightarrow \mathbb{C}$ for the map

$$\text{ev}_x(m) = z^m \text{ evaluated at } x$$

Each ev_x is a homomorphism of monoids from $M \cap \sigma$ to (\mathbb{C}, \times) . The universal property of the monoid ring gives the following

Proposition 1.6. *Let σ be a rational polyhedral cone in $M_{\mathbb{R}}$. Then $x \mapsto \text{ev}_x$ is a one-to-one correspondence between the complex points of $\text{Spec } \mathbb{C}[M \cap \sigma]$ and the monoid homomorphisms $M \cap \sigma \rightarrow \mathbb{C}$.*

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2. DEGENERATIONS OF HYPERSURFACES

We fix a lattice polytope $\Delta \subseteq M_{\mathbb{R}}$ with $0 \in \Delta$. Let $K \subseteq M_{\mathbb{R}}$ be a convex subset. A continuous function $h : K \rightarrow \mathbb{R}$ is called *convex* if for each $m, m' \in K$ and we have

$$\frac{h(m) + h(m')}{2} \geq h\left(\frac{m + m'}{2}\right).$$

We fix a lattice triangulation \mathcal{T}_{Δ} of Δ with the following property: $0 \in \mathcal{T}_{\Delta}^{[0]}$ and there exists a convex piecewise linear function $h : \mathbb{R}_{\geq 0}\Delta \rightarrow \mathbb{R}$ taking non-negative integral values on M such that the maximal dimensional simplices in \mathcal{T}_{Δ} coincide with the non-extendable closed domains of linearity of $h|_{\Delta}$. We also choose such a function, h . Triangulations with this property are often called *regular* or *coherent*. Every lattice polytope containing the origin supports a regular lattice triangulation. Since h is linear on the $(n+1)$ -simplices of \mathcal{T}_{Δ} , this triangulation is “star-shaped with center 0” in the sense that each simplex in \mathcal{T}_{Δ} is either contained in $\partial\Delta$ or else contains the origin 0. We define the triangulation \mathcal{T} by

$$\mathcal{T} = \{\tau \in \mathcal{T}_{\Delta} \mid \tau \subseteq \partial\Delta, 0 \notin \tau\},$$

i.e., the set of simplices of Δ not containing the origin. We denote the union of all $\tau \in \mathcal{T}$ by $|\mathcal{T}|$, and sometimes by $\partial\Delta'$. Since \mathcal{T} induces \mathcal{T}_{Δ} , we call \mathcal{T} regular if the induced \mathcal{T}_{Δ} is regular.

We fix a Laurent polynomial $f \in \mathbb{C}[M]$ of the form

$$(2.1) \quad f = a_0 + \sum_{m \in \mathcal{T}^{[0]}} a_m z^m.$$

We suppose that all coefficients are real, that $a_0 < 0$, that $a_m > 0$ for $m \in \mathcal{T}^{[0]}$, and that they are chosen generically with this property. We write $V(f) \subseteq \text{Spec } \mathbb{C}[M]$ for the hypersurface in the algebraic torus defined by $f = 0$.

Remark 2.1. Since the positivity conditions on the a_m are Zariski dense, it follows by Proposition 1.5 that $V(f)$ is smooth and diffeomorphic to any generic hypersurface whose Newton polytope is Δ .

Using the piecewise linear function h , we can give a toric degeneration of $(\mathbb{C}^*)^{n+1}$ and an induced degeneration of $V(f)$ in the style of Mumford. We construct this degeneration in Sections 2.1 and 2.2.

Remark 2.2. In case the origin is on the boundary of Δ , it is natural to embed $V(f)$ into the following partial compactification of $(\mathbb{C}^*)^{n+1}$. The polytope Δ generates a cone $\mathbb{R}_{\geq 0}\Delta \subseteq M_{\mathbb{R}}$. The cone is not usually strictly convex, e.g. if $0 \in \Delta^\circ$ then this cone is all of $M_{\mathbb{R}}$. In any case, f is always a linear combination of monomials in $\mathbb{R}_{\geq 0}\Delta \cap M$ and defines a hypersurface in $\text{Spec } \mathbb{C}[M \cap \mathbb{R}_{\geq 0}\Delta]$ which we denote by $\bar{V}(f)$. If $0 \in \Delta^\circ$, $\bar{V}(f) = V(f)$.

2.1. Degeneration of the ambient space. The total space of the degeneration will be an affine toric variety Y closely related to the affine cone over the projective toric variety whose moment polytope is Δ . More precisely, it is the affine cone over a blowup of this toric variety, or else an open subset of this affine cone. The construction makes use of the *overgraph cone* in $M_{\mathbb{R}} \oplus \mathbb{R}$, coming from the piecewise-linear function h .

2.1.1. The overgraph cone. Let $\Sigma_{\mathcal{T}}$ be the fan in $M_{\mathbb{R}}$ whose nonzero cones are the cones over the simplices in \mathcal{T} , i.e.,

$$\Sigma_{\mathcal{T}} = \{\mathbb{R}_{\geq 0}\tau \mid \tau \in \mathcal{T}\}.$$

When 0 is an interior lattice point, $\Sigma_{\mathcal{T}}$ is a complete fan. In general its support is the cone $\mathbb{R}_{\geq 0}\Delta$.

Since \mathcal{T} is regular, $\Sigma_{\mathcal{T}}$ is projected from part of the boundary of a rational polyhedral cone in $M_{\mathbb{R}} \oplus \mathbb{R}$. We fix such a cone and call it the *overgraph cone*. Let us define it more precisely. Set $\widetilde{M} = M \oplus \mathbb{Z}$ and $\widetilde{M}_{\mathbb{R}} = \widetilde{M} \otimes_{\mathbb{Z}} \mathbb{R}$. The overgraph cone of h is defined to be

$$\Gamma_{\geq h} = \{(m, r) \in \widetilde{M}_{\mathbb{R}} \mid m \in \mathbb{R}_{\geq 0}\Delta, r \geq h(m)\}$$

Each cone in $\Sigma_{\mathcal{T}}$ is isomorphic to a proper face of $\Gamma_{\geq h}$ under the projection $\widetilde{M}_{\mathbb{R}} \rightarrow M_{\mathbb{R}}$. The inverse isomorphism is given by $m \mapsto (m, h(m))$. Since h takes integral values on M , the faces of $\Gamma_{\geq h}$ that appear in this way form a rational polyhedral fan in \widetilde{M} . We record this observation in the following lemma:

Lemma 2.3. *Let $\mathbb{R}_{\geq 0}\tau$ be a cone in $\Sigma_{\mathcal{T}}$ and let $\Gamma_{\geq h, \tau} \subseteq \Gamma_{\geq h}$ be the face*

$$\Gamma_{\geq h, \tau} = \{(m, h(m)) \in \Gamma_{\geq h} \mid m \in \mathbb{R}_{\geq 0}\tau\}.$$

Then the projection $\Gamma_{\geq h, \tau} \rightarrow \mathbb{R}_{\geq 0}\tau$ is an isomorphism of cones inducing an isomorphism of monoids $\Gamma_{\geq h, \tau} \cap \widetilde{M} \rightarrow \mathbb{R}_{\geq 0}\tau \cap M$.

2.1.2. *Degeneration.* The overgraph cone determines an affine toric variety that we denote by Y , i.e.

$$Y = \operatorname{Spec} \mathbb{C}[\Gamma_{\geq h} \cap \widetilde{M}]$$

Define $t : Y \rightarrow \mathbb{C}$ to be the regular monomial function $z^{(0,1)}$ on Y . Let $Y_0 \subseteq Y$ denote the fiber $t^{-1}(0)$. Since t is a monomial, Y_0 is torus invariant in Y , but in general has many irreducible components. Let us call the components of $t^{-1}(0)$ the *vertical divisors* of the map t and the remaining toric divisors *horizontal divisors*.

Remark 2.4. Since Y is an affine toric variety, we can identify the points of Y (by Proposition 1.6) with the space of monoid homomorphisms $(\widetilde{M} \cap \Gamma_{\geq h}, +) \rightarrow (\mathbb{C}, \times)$. In this description, Y_0 is the subset of monoid homomorphisms $\phi : \widetilde{M} \cap \Gamma_{\geq h} \rightarrow \mathbb{C}$ carrying $(0, 1)$ to 0.

Proposition 2.5. *The map $t : Y \rightarrow \mathbb{C}$ has the following properties:*

- (1) $t^{-1}(\mathbb{C}^*) = \operatorname{Spec} \mathbb{C}[(\mathbb{R}_{\geq 0}\Delta) \cap M] \times \mathbb{C}^*$ and the restriction of t to $t^{-1}(\mathbb{C}^*)$ is the projection onto the second factor.
- (2) The subscheme structure on $Y_0 = t^{-1}(0)$ is reduced.
- (3) t is a toric degeneration of $\operatorname{Spec} \mathbb{C}[(\mathbb{R}_{\geq 0}\Delta) \cap M]$. The restriction of t to the complement of the union of horizontal divisors is a degeneration of $\operatorname{Spec} \mathbb{C}[M] \cong (\mathbb{C}^*)^{n+1}$.

Proof. Localizing to $t^{-1}(\mathbb{C}^*)$ means adjoining t^{-1} to the ring $\mathbb{C}[\Gamma_{\geq h} \cap \widetilde{M}]$ which yields $\mathbb{C}[(\mathbb{R}_{\geq 0}\Delta) + \mathbb{R}(0, 1)) \cap \widetilde{M}] = \mathbb{C}[(\mathbb{R}_{\geq 0}\Delta) \cap M] \otimes_{\mathbb{C}} \mathbb{C}[\mathbb{Z}]$. This gives the first statement in (3) as well as (1).

To prove (2), note that since h takes integral values on M , any element $m \in \Gamma_{\geq h} \cap \widetilde{M}$ can uniquely be written as

$$m' + k(0, 1)$$

with $k \in \mathbb{Z}_{\geq 0}$ and m' in $\Gamma_{\geq h, \tau} \cap \widetilde{M}$ for some $\tau \in \mathcal{T}$. The second statement in (3) is best seen in the fan picture. If Σ is the normal fan of $\Gamma_{\geq h}$, removing the horizontal divisors amounts to restricting to the subfan $\Sigma' \subseteq \Sigma$ of cones that have no rays contained in $(0, 1)^\perp$. The map t is given by mapping Σ' to the fan $\{\{0\}, \mathbb{R}_{\geq 0}\}$ and $\{0\} \in \Sigma'$ is the only cone that maps to $\{0\}$, so the general fiber is indeed an algebraic torus. \square

Let us describe the vertical and the horizontal divisors in more detail.

Proposition 2.6. *Let Y and t be as above and for each $\tau \in \mathcal{T}$ let $\Gamma_{\geq h, \tau}$ be as in Lemma 2.3.*

- (1) *The assignment $\tau \mapsto \operatorname{Spec} \mathbb{C}[\Gamma_{\geq h, \tau}]$ is a bijection between the vertical divisors of t and the n -dimensional simplices of \mathcal{T} .*
- (2) *The assignment*

$$\tau \mapsto \operatorname{Spec} \mathbb{C}[(\mathbb{R}_{\geq 0}\{(m, h(m)) \mid m \in \tau\} + \mathbb{R}_{\geq 0}(0, 1)) \cap \widetilde{M}]$$

is a bijection between the horizontal divisors of t and the n -dimensional simplices τ of \mathcal{T}_Δ with $0 \in \tau$.

Proof. The prime divisors in Y correspond to the codimension one faces of $\Gamma_{\geq h}$. Such a face corresponds to a vertical divisor if and only if it contains $(0, 1)$. This implies (1) and (2). \square

Example 2.7. Let us describe an example for $n = 1$, so $\Delta \subseteq M = \mathbb{Z}^2$ is a lattice polygon. We define Δ as the convex hull of $\{(0, 1), (-1, -1), (1, -1)\}$. We name the the lattice points in Δ as follows

$$\begin{array}{ccccc} \bullet & \bullet & \bullet & \bullet & \bullet \\ \bullet & \bullet & s & \bullet & \bullet \\ \bullet & \bullet & 0 & \bullet & \bullet \\ \bullet & p & q & r & \bullet \\ \bullet & \bullet & \bullet & \bullet & \bullet \end{array}$$

There are only two lattice triangulations of $\partial\Delta$: the canonical triangulation where the maximal simplices of \mathcal{T} are $\{\overline{ps}, \overline{rs}, \overline{pr}\}$, and the unimodular triangulation where the maximal simplices of \mathcal{T} are $\{\overline{ps}, \overline{rs}, \overline{pq}, \overline{qr}\}$

Let \mathcal{T} be the canonical triangulation, so that the maximal cones in $\Sigma_{\mathcal{T}}$ are $\mathbb{R}_{\geq 0}\overline{rs}$, $\mathbb{R}_{\geq 0}\overline{ps}$, and $\mathbb{R}_{\geq 0}\overline{pr}$. Let h be the piecewise linear function on $\Sigma_{\mathcal{T}}$ that takes the value 1 on the vertices of Δ . Then $\Gamma_{\geq h}$ is the simplicial cone in \mathbb{R}^3 with rays generated by $(0, 1, 1), (-1, -1, 1), (1, -1, 1)$. The ring of regular functions on Y is $\mathbb{C}[\Gamma_{\geq h} \cap \widetilde{M}]$ which we may identify with the quotient of $\mathbb{C}[p, q, r, s, t]$ by the ideal generated by

$$pr = q^2, \quad qs = t^2$$

(The identification sends the variable p to the lattice point $z^p t^{h(p)}$, etc.). We have $t^{-1}(\lambda) \cong \mathbb{C}^* \times \mathbb{C}^*$ for $\lambda \neq 0$ via $(p, q, r, s, t) \mapsto (p, q)$. The irreducible components of Y_0 are given by

- $V(p, q, t) = \text{Spec } \mathbb{C}[\Gamma_{h, \overline{rs}} \cap \widetilde{M}] \cong \{(r, s) \in \mathbb{C}^2\}$,
- $V(r, q, t) = \text{Spec } \mathbb{C}[\Gamma_{h, \overline{ps}} \cap \widetilde{M}] \cong \{(p, s) \in \mathbb{C}^2\}$,
- $V(s, t) = \text{Spec } \mathbb{C}[\Gamma_{h, \overline{pr}} \cap \widetilde{M}] \cong \{(p, q, r) \in \mathbb{C}^3 \mid pr = q^2\}$.

Remark 2.8. We have described this example using coordinates on Y indexed by the lattice points in Δ . This is always possible for $n \leq 1$. In general, additional generators might be needed.

2.1.3. Orbit closures in Y_0 . For each $\tau \in \mathcal{T}$ let $Y_{0, \tau}$ be the $(\dim(\tau) + 1)$ -dimensional affine toric variety

$$Y_{0, \tau} = \text{Spec } (\mathbb{C}[\widetilde{M} \cap \Gamma_{\geq h, \tau}])$$

where $\Gamma_{\geq h, \tau}$ is defined in Lemma 2.3. Since $\Gamma_{\geq h, \tau}$ is a face of $\Gamma_{\geq h}$, $Y_{0, \tau}$ is a torus orbit closure in Y . Each vertical divisor of t is of the form $Y_{0, \tau}$ where τ is an n -dimensional simplex of \mathcal{T} .

When τ is an n -dimensional simplex in τ (determining the $(n+1)$ -dimensional face $\Gamma_{\geq h, \tau} \subseteq \Gamma_{\geq h}$), $Y_{0, \tau}$ is a vertical divisor are the vertical divisors of Proposition 2.6. Every $Y_{0, \tau}$ is contained in some vertical divisor and in particular in Y_0 .

Restricting regular functions from Y to $Y_{0, \tau}$ induces the ring quotient map

$$\mathbb{C}[\Gamma_{\geq h} \cap \widetilde{M}] \rightarrow \mathbb{C}[\Gamma_{\geq h, \tau} \cap \widetilde{M}]$$

whose kernel is the ideal generated by monomials $z^{(m, r)}$ with $(m, r) \notin \Gamma_{\geq h, \tau}$. By Lemma 2.3, we may identify $\mathbb{C}[\Gamma_{\geq h, \tau} \cap \widetilde{M}]$ with $\mathbb{C}[\mathbb{R}_{\geq 0}\tau \cap M]$.

2.1.4. *Projection onto $\mathbb{P}^{\dim(\tau)}$.* The action of $\text{Hom}(M, \mathbb{C}^*)$ on $Y_{0,\tau}$ factors through an action of the quotient torus $\text{Hom}(\mathbb{R}\tau \cap M, \mathbb{C}^*)$. A finite subgroup $D_\tau \subseteq \text{Hom}(\mathbb{R}\tau \cap M, \mathbb{C}^*)$ will play an important role for us.

Definition 2.9. Let D_τ be the finite commutative group

$$D_\tau = \text{Hom}(\mathbb{R}\tau \cap M / \mathbb{Z}\tau^{[0]}, \mathbb{C}^*)$$

We regard D_τ as a subgroup of $\text{Hom}(\mathbb{R}\tau \cap M, \mathbb{C}^*)$, and let it act on the coordinate ring of $Y_{0,\tau} = \text{Spec } \mathbb{C}[M \cap \mathbb{R}_{\geq 0}\tau]$ by

$$d.z^m = d(m)z^m$$

Proposition 2.10. *The invariant subring*

$$\mathbb{C}[M \cap \mathbb{R}_{\geq 0}\tau]^{D_\tau} \subseteq \mathbb{C}[M \cap \mathbb{R}_{\geq 0}\tau]$$

is the monoid ring $\mathbb{C}[\mathbb{Z}_{\geq 0}\tau^{[0]}]$. In other words, it is a polynomial ring whose $\dim(\tau) + 1$ variables are parameterized by the vertices $\tau^{[0]}$ of τ .

Proof. The monomials z^m for $M \cap \mathbb{R}_{\geq 0}\tau$ form a basis of eigenvectors for the D_τ -action on $\mathbb{C}[M \cap \mathbb{R}_{\geq 0}\tau]$. The invariants are therefore generated by those monomials z^m for which $d(m) = 1$ for all $d \in D_\tau$. Each vertex of τ has this property, and thus

$$\mathbb{Z}_{\geq 0}\tau^{[0]} \subseteq \{m \in \mathbb{R}_{\geq 0}\tau \cap M \mid d(m) = 1 \text{ for all } d \in D_\tau\}$$

Let us show the containment is an equality, i.e. that for each $m \in M \cap \mathbb{R}_{\geq 0}\tau$, if the monomial z^m is D_τ -invariant then m is a $\mathbb{Z}_{\geq 0}$ -linear combination of the vertices of τ . This follows from the fact that $\tau^{[0]}$ is a basis for the vector space $\mathbb{R}\tau$, and that each element of $M \cap \mathbb{R}_{\geq 0}\tau$ can be written in this basis with coefficients in $\mathbb{Q}_{\geq 0}$. Indeed, let $v_0, v_1, \dots, v_{\dim(\tau)}$ be the vertices of τ and for $i = 0, \dots, \dim(\tau)$ define d_i by $d_i(v_j) = \delta_{i,j}$. Suppose that z^m is a D_τ -invariant monomial. Then since $m = \sum a_i v_i$ where each a_i is in $\mathbb{Q}_{\geq 0}$, we have $d_j(m) = e^{2\pi i a_j} = 1$ for all j , i.e. $a_j \in \mathbb{Z}_{\geq 0}$. \square

Proposition 2.11. *The fiber of the D_τ -quotient map*

$$Y_{0,\tau} \rightarrow \mathbb{C}^{\dim(\tau)+1}$$

above $0 \in \mathbb{C}^{\dim(\tau)+1}$ is a single point.

Note there is a mild abuse of notation here: the coordinates of $\mathbb{C}^{\dim(\tau)+1}$ are not indexed by the integers $1, \dots, n+1$ but the vertices of τ .

Proof. We use the description of Proposition 1.6. The origin in $\mathbb{C}^{\dim(\tau)+1}$ corresponds to the monoid homomorphism $\mathbb{Z}_{\geq 0}\tau^{[0]} \rightarrow \mathbb{C}$ that carries each vertex of τ (and in fact each nonzero element of $\mathbb{Z}_{\geq 0}\tau^{[0]}$) to $0 \in \mathbb{C}$. To prove the Proposition, it suffices to show that this extends to a monoid map $M \cap \mathbb{R}_{\geq 0}\tau \rightarrow \mathbb{C}$ in a unique way. Indeed, this is the map that carries 0 to 1 and each nonzero element of $M \cap \mathbb{R}_{\geq 0}\tau$ to 0 . \square

Since the D_τ -invariant ring $\mathbb{C}[\mathbb{Z}_{\geq 0}\tau^{[0]}]$ is a polynomial ring, we may endow it with a grading by declaring that $\deg(z^m) = 1$ whenever m is a vertex of τ .

Definition 2.12. Let $0 \in Y_{0,\tau}$ and $0 \in \text{Spec}(\mathbb{C}[\mathbb{Z}_{\geq 0}\tau^{[0]}])$ denote the points of Proposition 2.11. We define a space $\mathbb{P}^{\dim(\tau)}$ and a map $\pi_\tau : Y_{0,\tau} \setminus \{0\} \rightarrow \mathbb{P}^{\dim(\tau)}$ as follows:

- (1) We let $\mathbb{P}^{\dim(\tau)} = \text{Proj}(\mathbb{C}[\mathbb{Z}_{\geq 0}\tau^{[0]}])$, where the grading on the coordinate ring is indicated above. In other words, $\mathbb{P}^{\dim(\tau)}$ is a projective space whose homogeneous coordinates are naturally indexed by the vertices of τ .
- (2) We let $\pi_\tau : Y_{0,\tau} \setminus \{0\} \rightarrow \mathbb{P}^{\dim(\tau)}$ denote the composite map

$$Y_{0,\tau} \setminus \{0\} \rightarrow \mathbb{C}^{\dim(\tau)+1} \setminus \{0\} \rightarrow \mathbb{P}^{\dim(\tau)}$$

where the first map is the D_τ -quotient map of Proposition 2.10 and the second map is the tautological map.

Note the abuse of notation in (1): if $\dim(\tau) = \dim(\tau')$ we will usually regard $\mathbb{P}^{\dim(\tau)}$ as different from $\mathbb{P}^{\dim(\tau')}$.

2.2. Degeneration of the hypersurface. In Proposition 2.5, we have seen that the general fiber of $t : Y \rightarrow \mathbb{C}$ is isomorphic to $\text{Spec } \mathbb{C}[M \cap \mathbb{R}_{\geq 0}\Delta]$. We now describe a degeneration of $\bar{V}(f) \subseteq \text{Spec } \mathbb{C}[(\mathbb{R}_{\geq 0}\Delta) \cap M]$ contained in the family $t : Y \rightarrow \mathbb{C}$. The total space of the degeneration is the hypersurface in Y cut out by a regular function \tilde{f} on Y . On the open orbit of Y , \tilde{f} looks like

$$\tilde{f} = a_0 + \sum_{m \in \mathcal{T}^{[0]}} a_m z^{(m, h(m))} = a_0 + \sum_{m \in \mathcal{T}^{[0]}} a_m z^m t^{h(m)}$$

where the a_m are the same coefficients as in f (Equation 2.1). Denote the vanishing locus of \tilde{f} by $X = V(\tilde{f})$.

Remark 2.13. When 0 is in the interior of Δ , X is a degeneration of $V(f)$. When 0 is on the boundary, X is a degeneration of $\bar{V}(f) \supset V(f)$ defined in Remark 2.2.

Example 2.14. Let Δ be the convex hull of $\{(0, 1), (-1, -1), (1, -1)\}$ as in Example 2.7 and let \mathcal{T} be the canonical triangulation, with piecewise linear function h taking value 1 at each vertex of $\partial\Delta$. By Proposition 2.5, the space $t^{-1}(1) \subseteq Y$ is $\text{Spec } \mathbb{C}[M \cap \mathbb{R}_{\geq 0}\Delta] = \text{Spec } \mathbb{C}[M]$ which is a complex two-torus. We write $z^{(a,b)} = x^a y^b$ and $z^{(a,b,c)} = x^a y^b t^c$. On $t^{-1}(1)$ and on the open complex three-torus inside Y , the polynomials f and \tilde{f} are

$$\begin{aligned} f &= a_0 + a_p x^{-1} y^{-1} + a_r x y^{-1} + a_s y \\ \tilde{f} &= a_0 + a_p x^{-1} y^{-1} t + a_r x y^{-1} t + a_s y t \end{aligned}$$

We are interested in the hypersurface $Z = V(f) \subseteq \mathbb{C}^* \times \mathbb{C}^* = t^{-1}(1)$. Recall from Example 2.7 that Y is contained in the vector space with coordinates p, q, r, s, t subject to equations $pr = q^2$ and $qs = t^2$. In these global coordinates, we can write

$$\tilde{f} = a_0 + a_p p + a_r r + a_s s$$

and $X = V(\tilde{f}) \subseteq Y$. By setting $t = 1$, we see $Z \subseteq X$.

The restriction of \tilde{f} to $Y_{0,\tau}$ is the image of \tilde{f} under the ring quotient map

$$\mathbb{C}[\Gamma_{\geq h} \cap \widetilde{M}] \rightarrow \mathbb{C}[\Gamma_{\geq h,\tau} \cap \widetilde{M}]$$

that carries $z^{(m,r)}$ to itself if $(m, r) \in \Gamma_{\geq h,\tau}$ and to 0 otherwise. In other words, $\tilde{f}|_{Y_{0,\tau}}$ is given by

$$\tilde{f}|_{Y_{0,\tau}} = a_0 + \sum_{m \in \mathcal{T}^{[0]}} a_m z^{(m, h(m))}$$

Let us denote the image of $\tilde{f}|_{Y_{0,\tau}}$ under the identification $Y_{0,\tau} = \text{Spec } \mathbb{C}[\mathbb{R}\tau \cap M]$ by f_τ . We record this in the following definition:

Definition 2.15. Let a_m be the coefficients of f (Equation 2.1).

- (1) Let $f_\tau \in \mathbb{C}[\mathbb{R}_{\geq 0}\tau \cap M]$ denote the expression

$$f_\tau = a_0 + \sum_{m \in \tau^{[0]}} a_m z^m$$

regarded as a regular function on $Y_{0,\tau}$. Let $X_{0,\tau}$ be the hypersurface in $Y_{0,\tau}$ cut out by f_τ .

- (2) Let $\ell_\tau \in \mathbb{C}[\mathbb{Z}_{\geq 0}\tau^{[0]}]$ denote the expression

$$\ell_\tau = \sum_{m \in \tau^{[0]}} a_m z^m$$

regarded as a homogeneous linear function on $\mathbb{P}^{\dim(\tau)}$. Let $V(\ell_\tau) \subseteq \mathbb{P}^{\dim(\tau)}$ denote the hyperplane cut out by ℓ_τ .

Proposition 2.16. Fix $\tau \in \mathcal{T}$ and denote by $p_\tau : X_{0,\tau} \rightarrow \mathbb{P}^{\dim(\tau)}$ the composition

$$X_{0,\tau} \hookrightarrow Y_{0,\tau} \setminus \{0\} \xrightarrow{\pi_\tau} \mathbb{P}^{\dim(\tau)}$$

where the second map is the projection of Definition 2.12. Then

- (1) p_τ is a finite proper surjection onto the affine space $\mathbb{P}^{\dim(\tau)} \setminus V(\ell_\tau) \cong \mathbb{C}^{\dim(\tau)}$.
- (2) p_τ induces an isomorphism

$$X_{0,\tau}/D_\tau \cong \mathbb{P}^{\dim(\tau)} \setminus V(\ell_\tau)$$

where D_τ is as in Definition 2.9.

- (3) The ramification locus of p_τ is contained in the coordinate hyperplanes of $\mathbb{P}^{\dim(\tau)}$.

Proof. The following implicit assertions of the Proposition are trivial to verify:

- since $a_0 \neq 0$, the point $0 \in Y_{0,\tau}$ of Proposition 2.11 does not lie on $X_{0,\tau}$.
- since the monomials that appear in f_τ belong to $\mathbb{Z}_{\geq 0}\tau^{[0]}$, they are invariant under the action of D_τ

Note that (1) is a consequence of (2). Since $a_0 \neq 0$ the function $f_\tau = a_0 + \ell_\tau$ cannot vanish anywhere that ℓ_τ vanishes. Therefore the image of p_τ is contained in $\mathbb{P}^{\dim(\tau)} \setminus V(\ell_\tau)$. To complete the proof of (2), let us show that the affine coordinate ring R_1 of $\mathbb{P}^{\dim(\tau)} \setminus V(\ell_\tau)$ is the D_τ -invariant subring of the affine coordinate ring R_2 of $X_{0,\tau}$. We have

$$\begin{aligned} R_1 &= \mathbb{C}[\mathbb{Z}_{\geq 0}\tau^{[0]}]/(a_0 + \ell_\tau) \\ R_2 &= \mathbb{C}[M \cap \mathbb{R}_{\geq 0}\tau]/(f_\tau) \end{aligned}$$

and the short exact sequences

$$\begin{aligned} 0 &\longrightarrow \mathbb{C}[\mathbb{Z}_{\geq 0}\tau^{[0]}] \xrightarrow{a_0 + \ell_\tau} \mathbb{C}[\mathbb{Z}_{\geq 0}\tau^{[0]}] \longrightarrow R_1 \longrightarrow 0 \\ 0 &\longrightarrow \mathbb{C}[M \cap \mathbb{R}_{\geq 0}\tau] \xrightarrow{f_\tau} \mathbb{C}[M \cap \mathbb{R}_{\geq 0}\tau] \longrightarrow R_2 \longrightarrow 0 \end{aligned}$$

Part (2) of the Proposition is now a consequence of the observation that taking D_τ -invariants preserves exact sequences, and that $\mathbb{C}[\mathbb{Z}_{\geq 0}\tau] = \mathbb{C}[M \cap \mathbb{R}_{\geq 0}\tau]^{D_\tau}$ by Proposition 2.10.

Now let us prove (3). Let $H \subseteq \mathbb{P}^{\dim(\tau)}$ be the union of coordinate hyperplanes. By (2), to show that p_τ is unramified away from H it suffices to show that D_τ acts freely on $X_{0,\tau}$ away from $p_\tau^{-1}(H)$. In fact D_τ acts freely on $Y_{0,\tau} \setminus \pi^{-1}(H)$. This completes the proof. \square

2.3. Degeneration of the compact hypersurface. The families $t : Y \rightarrow \mathbb{C}$ and $t : X \rightarrow \mathbb{C}$ of Sections 2.1 and 2.2 have fairly natural algebraic relative compactifications (i.e., “properifications” of the maps t) that we review here.

We define the polyhedron

$$\bar{\Gamma} = \{(m, r) \in \widetilde{M}_{\mathbb{R}} \mid m \in \Delta, r \geq h(m)\}$$

which is contained in $\Gamma_{\geq h}$. We set $\tilde{N} = \text{Hom}(\widetilde{M}, \mathbb{Z})$, $\tilde{N}_{\mathbb{R}} = \tilde{N} \otimes_{\mathbb{Z}} \mathbb{R}$. The *normal fan* of $\bar{\Gamma}$ is the fan $\Sigma_{\bar{\Gamma}} = \{\sigma_\tau \mid \tau \subseteq \bar{\Gamma}\}$ where $\sigma_\tau = \{n \in \tilde{N}_{\mathbb{R}} \mid \langle m - m', n \rangle \geq 0 \text{ for all } m \in \bar{\Gamma}, m' \in \tau\}$ and $\langle \cdot, \cdot \rangle : \widetilde{M} \otimes \tilde{N} \rightarrow \mathbb{Z}$ is the natural pairing. Let \bar{Y} denote the toric variety associated to $\Sigma_{\bar{\Gamma}}$. It is covered by the set of affine open charts of the shape $\text{Spec } \mathbb{C}[\sigma_\tau^\vee \cap \widetilde{M}]$ where $\tau \in \bar{\Gamma}^{[0]}$ and

$$\sigma_\tau^\vee = \mathbb{R}_{\geq 0}\{m - m' \mid m \in \bar{\Gamma}, m' \in \tau\} \subseteq \widetilde{M}_{\mathbb{R}}$$

is the dual cone of σ_τ . Note that $\sigma_0^\vee = \Gamma_{\geq h}$, so we have an open embedding $Y \subseteq \bar{Y}$. Since $(0, 1) \in \sigma_\tau^\vee$ for all $\tau \subseteq \bar{\Gamma}$, t extends to a regular function

$$t : \bar{Y} \rightarrow \mathbb{C}.$$

The support of $\Sigma_{\bar{\Gamma}}$ is $\{(n, r) \in \tilde{N}_{\mathbb{R}} \mid r \geq 0\}$ and pairing with the monomial $(0, 1)$ sends this to $\mathbb{R}_{\geq 0}$. Thus by the Proposition in §2.4 of [Fu], we have

Lemma 2.17. $t : \bar{Y} \rightarrow \mathbb{C}$ is proper.

Corollary 2.18. Let \bar{X} denote the closure of X in \bar{Y} . Then $t : \bar{X} \rightarrow \mathbb{C}$, the restriction of t to \bar{X} , is proper.

3. THE SKELETON

3.1. Definition of the skeleton. We adopt the notation from §2, in particular $M \cong \mathbb{Z}^{n+1}$ is a lattice and $\Delta \subseteq M_{\mathbb{R}} = M \otimes_{\mathbb{Z}} \mathbb{R}$ a lattice polytope containing 0 and with regular lattice triangulation \mathcal{T} of $\partial\Delta'$. For $x \in \partial\Delta'$, let us denote by τ_x the lowest-dimensional simplex of \mathcal{T} containing x .

Definition 3.1. With Δ , \mathcal{T} , and $x \mapsto \tau_x$ given as above, define the topological subspace

$$S_{\Delta, \mathcal{T}} \subseteq \partial\Delta' \times \text{Hom}(M, S^1)$$

to be the set of pairs (x, ϕ) satisfying

$$\phi(v) = 1 \in S^1 \text{ whenever } v \in M \text{ is a vertex of } \tau_x.$$

The fibers of the projection $S_{\Delta, \mathcal{T}} \rightarrow \partial\Delta$ are constant above the interior of each simplex of \mathcal{T} . In fact these fibers are naturally identified with a subgroup of the torus $\text{Hom}(M, S^1)$. Let us introduce some notation for these fibers:

Definition 3.2. For each simplex $\tau \in \mathcal{T}$, let G_τ denote the commutative group contained in the torus $\text{Hom}(M, S^1)$ given by

$$G_\tau := \{\phi \in \text{Hom}(M, S^1) \mid \phi(v) = 1 \text{ whenever } v \in M \text{ is a vertex of } \tau\}$$

We denote the identity component of G_τ by A_τ and the discrete quotient $G_\tau/A_\tau = \pi_0(G_\tau)$ by D_τ . That is, we have the short exact sequence of abelian groups

$$(3.1) \quad 1 \rightarrow A_\tau \rightarrow G_\tau \rightarrow D_\tau \rightarrow 1.$$

This sequence can also be obtained by applying the exact contravariant functor $\text{Hom}(\cdot, S^1)$ to the sequence

$$0 \leftarrow M/((\mathbb{R}\tau) \cap M) \leftarrow M/(\mathbb{Z}\tau^{[0]}) \leftarrow ((\mathbb{R}\tau) \cap M)/(\mathbb{Z}\tau^{[0]}) \leftarrow 0.$$

On finite groups, $\text{Hom}(-, S^1) = \text{Hom}(-, \mathbb{C}^*)$, so the definition of D_τ given here agrees with Definition 2.9. Here are two additional properties of the groups G_τ :

- (1) A_τ is a compact torus of dimension $n - \dim(\tau)$.
- (2) When $\tau' \subseteq \tau$, there is a reverse containment $G_\tau \subseteq G_{\tau'}$.

Remark 3.3. The fiber of $S_{\Delta, \mathcal{T}} \rightarrow \partial\Delta'$ above x is connected if and only if D_{τ_x} is trivial, so if and only if the simplex $\text{conv}(\{0\} \cup \tau_x)$ is unimodular. A triangulation whose simplices are unimodular uses every lattice point of Δ as a vertex, but the converse is not true. For instance, τ might contain a triangle of the form $\{(1, 0, 0), (0, 1, 0), (1, 1, N)\}$ for $N > 1$.

Remark 3.4. Define an equivalence relation on $S_{\Delta, \mathcal{T}}$ by setting $x \sim y$ if both of the following hold:

- x and y project to the same element of $\partial\Delta'$,
- x and y are in the same connected component of the fiber of this projection.

If \mathcal{T} is unimodular, then the quotient $S_{\Delta, \mathcal{T}}/\sim$ is just $\partial\Delta'$.

In general it is some branched cover of $\partial\Delta'$, with stratum τ° having covering group D_τ . We may write it as a regular cell complex which we denote by $\widehat{\partial\Delta'}$, i.e.

$$\widehat{\partial\Delta'} := S_{\Delta, \mathcal{T}}/\sim \cong \bigcup_{\tau \in \mathcal{T}} \tau^\circ \times D_\tau.$$

We investigate this in more detail in the Section 3.2

Remark 3.5. The vertices of the triangulation \mathcal{T} generate the rays of a (stacky) fan $\Sigma^\vee \subseteq M_\mathbb{R}$. It is shown in [FLTZ, FLTZ2] that coherent sheaves on the toric Deligne-Mumford stack associated with Σ^\vee can be regarded as constructible sheaves on a compact torus with singular support in a conic Lagrangian $\Lambda_{\Sigma^\vee} \subseteq N_\mathbb{R}/N \times M_\mathbb{R} \cong T^*(N_\mathbb{R}/N)$. This “coherent-constructible correspondence” is a full embedding of triangulated categories — conjecturally an equivalence. The conic Lagrangian Λ_{Σ^\vee} is noncompact. Its Legendrian “boundary” $\Lambda_{\Sigma^\vee}^\infty$ at contact infinity of $T^*(N_\mathbb{R}/N)$ is homeomorphic to $S_{\Delta, \mathcal{T}}$ — see also Section 1.2.

3.2. $\widehat{\partial\Delta'}$ as a regular cell complex. Let us describe the combinatorics of $\widehat{\partial\Delta'}$ in some more detail.

Definition 3.6. For each $\tau \in \mathcal{T}$ let D_τ be the finite commutative group given in Definition 2.9. We define the partially ordered set $\widehat{\mathcal{T}}$ as follows.

- (1) If $\tau, \tau' \in \mathcal{T}$ have $\tau \subseteq \tau'$, define a homomorphism $\text{res}_{\tau', \tau} : D_{\tau'} \rightarrow D_{\tau}$ by the following formula. If $d : \mathbb{R}\tau' \cap M \rightarrow S^1$ is an element of $D_{\tau'}$, then $\text{res}_{\tau', \tau}(d) : \mathbb{R}\tau \cap M \rightarrow S^1$ is given by

$$\text{res}_{\tau', \tau}(d)(m) = d(m)$$

- (2) Let $\widehat{\mathcal{T}}$ denote the set of pairs (τ, d) where $\tau \in \mathcal{T}$ and $d \in D_{\tau}$. We regard $\widehat{\mathcal{T}}$ as a partially ordered set with partial order given by

$$(\tau, d) \leq (\tau', d') \text{ whenever } \tau \subseteq \tau' \text{ and } \text{res}_{\tau', \tau}(d') = d$$

Each $(\tau, d) \in \widehat{\mathcal{T}}$ determines a map

$$i_{\tau, d} : \tau \rightarrow \widehat{\partial\Delta'}$$

by the formula

$$i_{\tau, d}(m) = \{m\} \times d$$

Proposition 3.7. *For each $\tau \in \mathcal{T}$ and $d \in D_{\tau}$, and let $i_{\tau, d}$ be the map defined above. The following hold:*

- (1) *For each $\tau \in \mathcal{T}$ and $d \in D_{\tau}$, the map $i_{\tau, d}$ is a homeomorphism of τ onto its image $i_{\tau, d}(\tau) \subseteq \widehat{\partial\Delta'}$.*
(2) *Let (τ, d) and (τ', d') be elements of $\widehat{\mathcal{T}}$ and set $\tau'' = \tau \cap \tau'$. If τ'' is nonempty and $\text{res}_{\tau, \tau''}(d) = \text{res}_{\tau', \tau''}(d')$, then (letting d'' denote the common value of d and d' in $D_{\tau''}$)*

$$i_{\tau, d}(\tau) \cap i_{\tau', d'}(\tau') = i_{\tau'', d''}(\tau'')$$

- (3) *Let (τ, d) , (τ', d') , and τ'' be as in (2). If τ'' is empty, or if $\text{res}_{\tau, \tau''}(d) \neq \text{res}_{\tau', \tau''}(d')$, then*

$$i_{\tau, d}(\tau) \cap i_{\tau', d'}(\tau') = \emptyset$$

In other words, $\widehat{\partial\Delta'}$ is a regular cell complex whose partially ordered set of cells is naturally isomorphic to $\widehat{\mathcal{T}}$.

Proof. Note that the composite $\tau \rightarrow \widehat{\partial\Delta'} \rightarrow \partial\Delta'$ is the usual inclusion of τ into $\partial\Delta'$. Since τ is compact and $\widehat{\partial\Delta'}$ is Hausdorff, this proves (1). Let us now prove (2). Suppose $i_{\tau, d}(t) = i_{\tau', d'}(t')$. Then $t = t'$ and $d(t) = d'(t')$. Thus $t \in \tau \cap \tau' = \tau''$ and $d(t) = d''(t)$ as claimed. Now (3) is a direct consequence of (2). \square

Remark 3.8. In fact the Proposition shows that $\widehat{\partial\Delta'}$ is a “ Δ -complex” in the sense of [Hat, 2.1], or a “generalized simplicial complex” in the sense of [Koz, Definition 2.41].

Remark 3.9. We will use the following device for constructing continuous maps out of $\widehat{\partial\Delta'}$ or X_0 :

- (1) Let K be a regular cell complex, let $\{\kappa\}$ be the poset of cells, and let L be a topological space. If $\{j_{\kappa} : \kappa \rightarrow L\}$ is a system of continuous maps such that $j_{\kappa}|_{\kappa'} = j_{\kappa'}$ whenever $\kappa' \subseteq \kappa$, then there is a unique continuous map $j : K \rightarrow L$ with $j|_{\kappa} = j_{\kappa}$ for all κ .
(2) Let L be a topological space. If $\{j_{\tau} : X_{0, \tau} \rightarrow L\}_{\tau \in \mathcal{T}}$ is a system of continuous maps such that $j_{\tau}|_{\tau'} = j_{\tau'}$ whenever $\tau' \subseteq \tau$, then there is a unique continuous map $j : X_0 \rightarrow L$ with $j|_{\tau} = j_{\tau}$ for all τ .

In other words, K is a colimit of its cells and X_0 is a colimit of the components $X_{0, \tau}$.

Remark 3.10. For each $\tau \in \mathcal{T}$, $i_{\tau,1}$ be the embedding $\tau \hookrightarrow \widehat{\partial\Delta'}$ where the “1” in the subscript indicates the identity element of D_τ . These assemble to an inclusion $\partial\Delta' \hookrightarrow \widehat{\partial\Delta'}$ by Remark 3.9.

3.2.1. *The homotopy type of $\widehat{\partial\Delta'}$.* It is easy to identify the homotopy type of $\widehat{\partial\Delta'}$, using the technique of “shelling.”

Theorem 3.11. *The regular cell complex $\widehat{\partial\Delta'}$ has the homotopy type of a wedge of n -dimensional spheres.*

Proof. We will show that $\widehat{\partial\Delta'}$ is *shellable* in the sense of [Koz, Definition 12.1]—then by [Koz, Theorem 12.3] $\widehat{\partial\Delta'}$ is homotopy equivalent to a wedge of n -dimensional spheres. By [BM, Proposition 1], the triangulation \mathcal{T} of $\partial\Delta'$ has a shellable subdivision, denote it by \mathcal{S} . Let $\widehat{\mathcal{S}}$ denote the lift of \mathcal{S} to $\widehat{\partial\Delta'}$. For each top-dimensional face σ of \mathcal{S} , fix a total order $F(\sigma, 1), \dots, F(\sigma, k)$. Since $\widehat{\partial\Delta'} \rightarrow \partial\Delta'$ is a branched covering along the simplices of \mathcal{S} , whenever $\sigma_1, \sigma_2, \dots, \sigma_N$ is a shelling of \mathcal{S}

$$F(\sigma_1, 1), \dots, F(\sigma_1, k_1), F(\sigma_2, 1), F(\sigma_2, 2), \dots, F(\sigma_2, k_2), \dots, F(\sigma_N, 1), \dots, F(\sigma_N, k_N)$$

is a shelling of $\widehat{\mathcal{S}}$. □

3.3. **Embedding $\widehat{\partial\Delta'}$ into X_0 .** In this section, using the positivity conditions on the coefficients a_m of f described below Equation (2.1), we will construct an embedding of $\widehat{\partial\Delta'}$ into the special fiber X_0 .

3.3.1. *General remarks on positive loci in toric varieties.* Let $T \cong (\mathbb{C}^*)^n$ be an algebraic torus and fix a splitting $T \cong \mathrm{U}(1)^n \times \mathbb{R}_{>0}^n$. If W is a toric variety acted on by T , and $1 \in W$ is a base point in the open orbit, then the *positive locus* of W is the $\mathbb{R}_{>0}^n$ -orbit of 1 on W . The *nonnegative locus* is the closure of the positive locus. We write $W_{>0}$ for the positive locus and $W_{\geq 0}$ for the nonnegative locus.

Example 3.12. Let W be an affine toric variety of the form $\mathrm{Spec}(\mathbb{C}[M \cap \sigma])$. Then under the identification $W \cong \mathrm{Hom}(M \cap \sigma, \mathbb{C})$ of Proposition 1.6, the nonnegative locus is

$$(3.2) \quad W_{\geq 0} \cong \mathrm{Hom}(M \cap \sigma, \mathbb{R}_{\geq 0})$$

When $W = \mathrm{Proj}(\mathbb{C}[\mathbb{Z}_{\geq 0}^{n+1}])$, the nonnegative locus is the set of points whose homogeneous coordinates can be chosen to be nonnegative real numbers. It can be identified with a simplex. The following Proposition investigates this example in more detail:

Proposition 3.13. *Let $\tau \subseteq M_{\mathbb{R}}$ be a lattice simplex, and let $\mathbb{P}^{\dim(\tau)}$ be the projective space of Definition 2.12. Let $[x_m]_{m \in \tau[0]}$ be homogeneous coordinates for a point of $\mathbb{P}^{\dim(\tau)}$. Define the moment map $\mu_\tau : \mathbb{P}^{\dim(\tau)} \rightarrow M_{\mathbb{R}}$ by*

$$\mu_\tau([x_m]_{m \in \tau[0]}) = \frac{\sum_{m \in \tau[0]} |x_m|^2 m}{\sum_{m \in \tau[0]} |x_m|^2}$$

Then μ_τ is a homeomorphism of $\mathbb{P}_{\geq 0}^{\dim(\tau)}$ onto τ .

Proof. See [Fu, §4.2] □

Remark 3.14. The map of Proposition 3.13 is the usual moment map for a Hamiltonian torus action and symplectic form on $\mathbb{P}^{\dim(\tau)}$, but the conclusion of the Proposition holds for any map of the form

$$\frac{\sum_{m \in \tau^{[0]}} |x_m|^e m}{\sum_{m \in \tau^{[0]}} |x_m|^e}$$

so long as e is real and $e > 0$. When $e > 1$, these maps are smooth. The case $e = 1$ may lead to a simpler formula for the map considered in Definition 4.19

Remark 3.15. The moment maps of Proposition 3.13 have the following compatibility feature: if $\tau' \subseteq \tau$ is a face of τ , then the restriction of μ_τ to $\mathbb{P}^{\dim(\tau')} \subseteq \mathbb{P}^{\dim(\tau)}$ is $\mu_{\tau'}$. In particular, there is a well defined map

$$\nu : X_0 \rightarrow \partial \Delta' \subseteq M_{\mathbb{R}},$$

such that, for all τ , its restriction to $X_{0,\tau}$ is given by $\nu_\tau := \mu_\tau \circ p_\tau$.

3.3.2. *Embedding.* Recall the D_τ -equivariant maps

$$p_\tau : X_{0,\tau} \rightarrow \mathbb{P}^{\dim(\tau)} \setminus V(\ell_\tau)$$

of Proposition 2.16. We use it to define a *nonnegative locus* in $X_{0,\tau}$.

Definition 3.16. Fix $\tau \in \mathcal{T}$. Let $\mathbb{P}^{\dim(\tau)}$ be the projective space of Definition 2.12, let $X_{0,\tau}$ be the affine variety of Definition 2.15. We define subsets

$$\begin{array}{ccccc} \mathbb{P}_{>0}^{\dim(\tau)} & \subseteq & \mathbb{P}_{\geq 0}^{\dim(\tau)} & \subseteq & \mathbb{P}^{\dim(\tau)} \\ (X_{0,\tau})_{>0} & \subseteq & (X_{0,\tau})_{\geq 0} & \subseteq & X_{0,\tau} \end{array}$$

as follows:

- (1) Let $\mathbb{P}_{>0}^{\dim(\tau)} \subseteq \mathbb{P}^{\dim(\tau)}$ be the set of points whose homogeneous coordinates can be chosen to be positive real numbers. We call $\mathbb{P}_{>0}^{\dim(\tau)}$ the *positive locus* of $\mathbb{P}^{\dim(\tau)}$.
- (2) Let $\mathbb{P}_{\geq 0}^{\dim(\tau)} \subseteq \mathbb{P}^{\dim(\tau)}$ be the closure of $\mathbb{P}_{>0}^{\dim(\tau)}$, i.e. the set of points whose homogeneous coordinates can be chosen to be nonnegative real numbers. We call $\mathbb{P}_{\geq 0}^{\dim(\tau)}$ the *nonnegative locus* of $\mathbb{P}^{\dim(\tau)}$.
- (3) If $(Y_{0,\tau})_{\geq 0}$ is as defined in Example 3.12, let $(X_{0,\tau})_{\geq 0} = X_{0,\tau} \cap (Y_{0,\tau})_{\geq 0}$,

Proposition 3.17. Let $\mathbb{P}_{\geq 0}^{\dim(\tau)}$ be as in Definition 3.16 and let $V(\ell_\tau)$ be as in Definition 2.15. The following hold

- (1) $V(\ell_\tau)$ does not meet $\mathbb{P}_{\geq 0}^{\dim(\tau)}$, i.e.

$$V(\ell_\tau) \cap \mathbb{P}_{\geq 0}^{\dim(\tau)} = \emptyset$$

- (2) The projection of $X_{0,\tau}$ onto $\mathbb{P}^{\dim(\tau)} \setminus V(\ell_\tau)$ induces a homeomorphism of nonnegative loci

$$(X_{0,\tau})_{\geq 0} \xrightarrow{\sim} \mathbb{P}_{\geq 0}^{\dim(\tau)}$$

Proof. Suppose $[x_m]_{m \in \tau^{[0]}}$ are homogeneous coordinates for a point $P \in \mathbb{P}^{\dim(\tau)}$. If P belongs to the nonnegative locus, then by definition we may choose the x_m to be real and nonnegative. Moreover, at least one of the x_m must be nonzero, say x_{m_0} . Then evaluating ℓ_τ on P gives

$$\ell_\tau(P) = \sum_{m \in \tau^{[0]}} a_m x_m \geq a_{m_0} x_{m_0} > 0$$

since all the a_m are positive real numbers. In particular $\ell_\tau(P) \neq 0$. This proves (1).

Let us prove (2). Let $v_0, \dots, v_{\dim(\tau)}$ be the vertices of τ . A point of $(Y_{0,\tau})_{\geq 0}$ is given by a monoid homomorphism $x : M \cap \mathbb{R}_{\geq 0}\tau \rightarrow \mathbb{R}_{\geq 0}$. Since $\mathbb{R}_{\geq 0}$ is divisible and $\tau^{[0]}$ is a basis for $\mathbb{R}\tau$, x is determined by its values on $\tau^{[0]}$, and the map

$$x \mapsto (x(v_0), \dots, x(v_{\dim(\tau)}))$$

is an isomorphism of $(Y_{0,\tau})_{\geq 0}$ onto $\mathbb{R}_{\geq 0}^{\dim(\tau)+1}$. In these coordinates, the equation $f_\tau = 0$ defining $(X_{0,\tau})_{\geq 0}$ is

$$\sum_{i=0}^{\dim(\tau)} a_{v_i} x(v_i) = -a_0$$

which (since $a_0 < 0$ and $a_{v_i} > 0$) is a simplex with a vertex on each coordinate ray of $\mathbb{R}_{\geq 0}^{\dim(\tau)+1}$. It follows that the projection onto $(\mathbb{R}_{\geq 0}^{\dim(\tau)+1} \setminus \{0\})/\mathbb{R}_{>0} \cong \mathbb{P}_{\geq 0}^{\dim(\tau)}$ is an isomorphism. \square

To define an embedding $\widehat{\partial\Delta'} \rightarrow X_0$, we may appeal to Remark 3.9 and define map it simplex by simplex.

Definition 3.18. Let $\widehat{\mathcal{T}}$ be the poset of Definition 3.6. For each $(\tau, d) \in \widehat{\mathcal{T}}$ define the map $j_{\tau,d}$ to be the composite

$$\tau \xrightarrow{\mu^{-1}} \mathbb{P}_{\geq 0}^{\dim(\tau)} \xrightarrow{p_\tau^{-1}} (X_{0,\tau})_{\geq 0} \xrightarrow{d} (X_{0,\tau})_{\geq 0}$$

where

- μ^{-1} is the inverse homeomorphism to the map of Proposition 3.13
- p_τ^{-1} is the inverse homeomorphism to the map of Proposition 3.17(2).
- d denotes the action of $d \in D_\tau$ on $X_{0,\tau}$ of Definition 2.9.

Proposition 3.19. Let $\widehat{\partial\Delta'}$ be as in Remark 3.4, let $\widehat{\mathcal{T}}$ be as in Definition 3.6, and for each $(\tau, d) \in \widehat{\mathcal{T}}$ let $i_{\tau,d} : \tau \hookrightarrow \widehat{\partial\Delta'}$ be the inclusion defined in Section 3.2 and let $j_{\tau,d}$ be the inclusion of 3.18. There is a unique map $j : \widehat{\partial\Delta'} \hookrightarrow X_0$ such that for all $(\tau, d) \in \widehat{\mathcal{T}}$, the square

$$\begin{array}{ccc} \tau & \xrightarrow{j_{\tau,d}} & X_{0,\tau} \\ i_{\tau,d} \downarrow & & \downarrow \\ \widehat{\partial\Delta'} & \xrightarrow{j} & X_0 \end{array}$$

commutes.

Proof. By Remark 3.9(1), it suffices to show that the maps $\tau \rightarrow X_0$ given by $j_{\tau,d}$ are compatible in the sense that $j_{\tau,d}|_{\tau'} = j_{\tau', \text{res}_{\tau,\tau'}(d)}$ whenever $\tau' \subseteq \tau$. To see this, note that if $t' \in \tau' \subseteq \tau$, then μ^{-1} carries t' to $\mathbb{P}_{\geq 0}^{\dim \tau'} \subseteq \mathbb{P}_{\geq 0}^{\dim \tau}$ (see Remark 3.15). The proof of Prop. 3.17 shows that $p_{\tau'}^{-1}$ and p_τ^{-1} agree on this locus. Finally, the actions of d and $\text{res}_{\tau,\tau'}(d)$ are defined to agree on the result. \square

Remark 3.20. The inverse image above $\tau \subseteq \partial\Delta'$ of the map $\widehat{\partial\Delta'} \rightarrow \partial\Delta'$ is a mild generalization (to Fermat hypersurfaces in weighted projective spaces) of the space considered in [De, pp. 88–90].

3.4. $\widehat{\partial\Delta'}$ embeds in X_0 as a deformation retract. In this section we prove that the inclusion $\widehat{\partial\Delta'} \hookrightarrow X_0$ is a deformation retract. This is a “degenerate” case of our Main Theorem, and plays an important role in the proof.

3.4.1. Lifting deformation retractions along branched covers. Let us first discuss a path-lifting property of branched coverings:

Definition 3.21. Let W be a locally contractible, locally compact Hausdorff space and let $F_1 \subseteq F_2 \subseteq \cdots \subseteq F_k \subseteq W$ be a filtration by closed subsets.

- (1) A map $p : W' \rightarrow W$ is *branched along the filtration F* if it is proper and if $p^{-1}(F_i \setminus F_{i-1}) \rightarrow F_i \setminus F_{i-1}$ is a covering space for every i .
- (2) A path $\gamma : [0, 1] \rightarrow W$ is called an *enter path for the filtration F* if whenever $\gamma(t) \in F_i$, then $\gamma(s) \in F_i$ for all $s > t$. (In other words once γ enters the subset F_i , it does not leave). Write $\text{Maps}_F([0, 1], W)$ for the space of enter paths for F , with the compact-open topology.
- (3) A deformation retraction $W \rightarrow \text{Maps}([0, 1], W)$ that factors through $\text{Maps}_F([0, 1], W)$ is called a *F -deformation retraction*.

Proposition 3.22. Let $p : W' \rightarrow W$ be branched along a filtration F of W . Let $\gamma : [0, 1] \rightarrow W$ be an enter path for F . Then for each $w' \in p^{-1}(\gamma(0))$, there is a unique path $\tilde{\gamma} : [0, 1] \rightarrow W'$ with $p \circ \tilde{\gamma} = \gamma$ and $\tilde{\gamma}(0) = w'$. The path $\tilde{\gamma}$ is an enter path for $p^{-1}(F)$, and the map

$$W' \times_{p, \text{ev}_0} \text{Maps}_F([0, 1], W) \rightarrow \text{Maps}_{p^{-1}(F)}([0, 1], W')$$

that sends (w', γ) to the unique lift $\tilde{\gamma}$ is continuous.

Proof. This follows by a modification of the standard argument for covering spaces. See [Wo, Proposition 4.2] and also [Fo]. \square

Corollary 3.23. Suppose $p : W' \rightarrow W$ is branched along a filtration F of W . Suppose that $r : W \rightarrow \text{Maps}_F([0, 1], W)$ is an F -deformation retraction (in the sense of Definition 3.21) onto a subset $K \subseteq W$. Then $p^{-1}(K)$ is a $p^{-1}(F)$ -deformation retract of W' .

Proof. The composite map

$$W' \rightarrow W' \times_{p, \text{ev}_0} \text{Maps}_F([0, 1], W) \rightarrow \text{Maps}_F([0, 1], W')$$

where the first map is $w' \mapsto (w', r(p(w')))$ and the second map is the map of Proposition 3.22 is a deformation retraction of W' onto $p^{-1}(K)$. \square

In proving Theorem 4.26, we will have to consider maps which have similar features to the branched covers of Section 3.4.1, except on each stratum they restrict to more general principal bundles. Lemma 3.24 is a slight variant of Corollary 3.23, which works for this larger class of maps as well.

Lemma 3.24 (A slight variant of Corollary 3.23). Let $p : W_1 \rightarrow W_2$ be a continuous map, and let $K_2 \subseteq W_2$ be a closed deformation retract. Suppose that the restriction $p^{-1}(W_2 \setminus K_2) \rightarrow$

$W_2 \setminus K_2$ can be equipped with the structure of a principal bundle. Then $p^{-1}(K_2)$ is a deformation retract of W_1 .

Proof. Set $K_1 = p^{-1}(K_2)$. Let us call a path $\gamma : [0, 1] \rightarrow W_2$ a K_2 -constant path if it has the following property: if $\gamma(t) \in K_2$ then $\gamma(s) = \gamma(t)$ for all $s > t$. In other words, once γ enters K_2 , it is constant. Similarly let us define a K_1 -constant path in W_1 if once it enters K_1 , it is constant.

Recall that, given any principal bundle, it is always possible to endow it with a connection. Thus, we can enhance the map $p : p^{-1}(W_2 \setminus K_2) \rightarrow W_2 \setminus K_2$ to a principal bundle with connection. Using the connection, a K_2 -constant path $\gamma : [0, 1] \rightarrow W_2$ can be lifted in a unique way to $\tilde{\gamma} : [0, 1] \rightarrow W_1$ once the initial point $\tilde{\gamma}(0)$ is specified, and the assignment

$$W_1 \times \{K_2\text{-constant paths in } W_2\} \rightarrow \{K_1\text{-constant paths in } W_1\}$$

is continuous.

A deformation retraction of W_2 onto K_2 is given by a map $r : W_2 \rightarrow \text{Maps}([0, 1], W_2)$ such that

- $r(w)(0) = w$ for all w
- $r(w)(1) \in K_2$ for all w
- $r(w)(t) = w$ for all $w \in K_2$ and all t

For each w , the path $r(w) : [0, 1] \rightarrow W_2$ is a K_2 -constant path. Now we may define a map $r_1 : W_1 \rightarrow \text{Maps}([0, 1], W_1)$ by the formula

$$r_1(w_1) = \text{lift of } p \circ r_1(w_1) \text{ to } W_2 \text{ with initial point } w_1.$$

□

3.4.2. Retraction onto $\widehat{\partial\Delta'}$.

Definition 3.25. The *standard toric filtration* of a toric variety W is the filtration

$$F_0 \subseteq F_1 \subseteq F_2 \subseteq \cdots \subseteq W$$

where each F_i is the union of the torus orbits of dimension i or less.

Proposition 3.26. Let $\tau \subseteq M$ be a lattice simplex, let $\mathbb{P}^{\dim(\tau)}$ be the projective space of Definition 2.12, and let $\mathbb{P}_{\geq 0}^{\dim(\tau)}$ be the nonnegative locus of $\mathbb{P}^{\dim(\tau)}$ in the sense of Definition 3.16. Let ℓ be a homogeneous linear form on $\mathbb{P}^{\dim(\tau)}$ that does not vanish on $\mathbb{P}_{\geq 0}^{\dim(\tau)}$. Let F be the restriction of the standard toric filtration on $\mathbb{P}^{\dim(\tau)}$ to $\mathbb{P}^{\dim(\tau)} \setminus V(\ell)$. Then

- (1) There is an F -deformation retraction

$$r : \mathbb{P}^{\dim(\tau)} \setminus V(\ell) \rightarrow \text{Maps}_F([0, 1], \mathbb{P}^{\dim(\tau)} \setminus V(\ell))$$

onto $\mathbb{P}_{\geq 0}^{\dim(\tau)}$

- (2) r may be chosen so that for any face $\tau' \subseteq \tau$, the restriction of r to $\mathbb{P}^{\dim(\tau')}$ is an F' -deformation retraction of $\mathbb{P}^{\dim(\tau')} \setminus V(\ell')$ onto $\mathbb{P}_{\geq 0}^{\dim(\tau')}$. Here ℓ' is the restriction of ℓ to $\mathbb{P}^{\dim(\tau')}$ and F' is the restriction of F to $\mathbb{P}^{\dim(\tau')} \setminus V(\ell')$.

Proof. For any two points P, Q in $\mathbb{P}^{\dim(\tau)} \setminus V(\ell)$, let \overline{PQ} be the real line segment between them. Since each F_i is an affine subspace, if P and Q are in F_i then so is \overline{PQ} . To produce an F -deformation retraction, it is enough to find a map $s : \mathbb{P}^{\dim(\tau)} \setminus V(\ell) \rightarrow \mathbb{P}_{\geq 0}^{\dim(\tau)}$ so that

- $s(P) = P$ for all $P \in \mathbb{P}_{\geq 0}^{\dim(\tau)}$.
- $s(F_i) \subseteq F_i$ for all i

In that case the map r given by $r(Q) = \overline{Qs(Q)}$ in an F -deformation retraction. A suitable s is given by the moment map of Proposition 3.13, and by Remark 3.15, the deformation retractions we build in this way will have property (2) of the Proposition. \square

Theorem 3.27. *The inclusion $\widehat{\partial\Delta'} \hookrightarrow X_0$ admits a deformation retraction.*

Proof. Since $X_{0,\tau} \rightarrow \mathbb{P}^{\dim(\tau)} \setminus V(\ell_\tau)$ is a branched cover over the standard toric filtration of $\mathbb{P}^{\dim(\tau)}$, Proposition 3.26 and Corollary 3.23 together imply that $p_\tau^{-1}(\mathbb{P}_{\geq 0}^{\dim(\tau)})$ is a deformation retract of $X_{0,\tau}$. Moreover by part (2) of Proposition 3.26, these deformation retractions are compatible with inclusions $X_{0,\tau'} \subseteq X_{0,\tau}$. By Remark 3.9, they therefore assemble to a deformation retraction of X_0 to $\widehat{\partial\Delta'}$. \square

4. LOG GEOMETRY AND THE KATO-NAKAYAMA SPACE

We recall the definition of a log space X^\dagger from [Ka89] and the associated Kato-Nakayama space X_{\log} from [KN99] and [NO10]. We work with log structures in the analytic topology, which are treated in [KN99].

4.1. Log structures and log smoothness. For us, a *monoid* is a set with binary operation that is commutative, associative and has a unit. For each monoid \mathbf{M} , there is a unique group \mathbf{M}^{gp} called the *Grothendieck group of \mathbf{M}* together with a map $\mathbf{M} \rightarrow \mathbf{M}^{\text{gp}}$ satisfying the universal property that every homomorphism from \mathbf{M} to a group factors uniquely through $\mathbf{M} \rightarrow \mathbf{M}^{\text{gp}}$. A monoid is called *integral* if $\mathbf{M} \rightarrow \mathbf{M}^{\text{gp}}$ is injective. Equivalently, the cancellation law holds in \mathbf{M} : $ab = ac \Rightarrow b = c$. A finitely generated and integral monoid is called *fine*. An integral monoid \mathbf{M} is called *saturated* if $x \in \mathbf{M}^{\text{gp}}$, $x^n \in \mathbf{M}$ implies $x \in \mathbf{M}$. A finitely generated, saturated monoid is called *toric*.

Example 4.1. If $\sigma \subseteq \mathbb{R}^k$ is a rational polyhedral cone, then $\mathbb{Z}^k \cap \sigma$ is a toric monoid.

Let X be an analytic space. A *pre-log structure* for X is a sheaf of monoids \mathcal{M}_X together with a map of monoids $\alpha_X : \mathcal{M}_X \rightarrow \mathcal{O}_X$ where we use the multiplicative structure for the structure sheaf. We call $(\mathcal{M}_X, \alpha_X)$ a *log structure* if α_X induces an isomorphism on invertible elements $\mathcal{M}_X^\times \xrightarrow{\sim} \mathcal{O}_X^\times$. Given a (pre-)log structure $(\mathcal{M}_X, \alpha_X)$, the triple $X^\dagger = (X, \mathcal{M}_X, \alpha_X)$ is called a (pre-)log space. Pre-log spaces naturally form a category on which we have a forgetful functor to the category of analytic spaces via $X^\dagger \mapsto X$. This functor factors through the category of log spaces by the functor which associates a log structure to a pre-log structure. This is done by replacing $(\mathcal{M}_X, \alpha_X)$ by the *associated log structure* $(\mathcal{M}_X^a, \alpha_X^a)$ given as

$$\mathcal{M}_X^a = (\mathcal{M}_X \oplus \mathcal{O}_X^\times) / \{(m, \alpha_X(m)^{-1}) \mid m \in \mathcal{M}_X^\times = \alpha_X^{-1} \mathcal{O}_X^\times\}$$

with $\alpha_X^a(m, f) = f \cdot \alpha_X(m)$. Most of the time we will omit α_X , assume it as known and refer to a log structure just by its sheaf of monoids.

Example 4.2. If (X, \mathcal{O}_X) is an analytic space, the *trivial log structure* on X is given by $\mathcal{M}_X = (\mathcal{O}_X)^\times$, with α_X the inclusion map.

Example 4.3. If (X, \mathcal{O}_X) is an analytic space and $D \subseteq X$ a divisor, the *divisorial log structure* $\mathcal{M}_{(X,D)}$ on X is given by $\mathcal{M}_{(X,D)} = \mathcal{O}_X \cap j_* \mathcal{O}_{X \setminus D}^\times$, with $j : X \setminus D \rightarrow X$ the open embedding and α_X the inclusion map.

4.1.1. *The standard toric log structure on a toric variety.* Each toric variety W has a natural divisor D which is the complement of the open torus. Thus by Example 4.3, W carries the divisorial log structure $\mathcal{M}_{(W,D)}$ which we call the standard log structure on W . We give another description for it in here.

Definition 4.4. A log space (W, \mathcal{M}_W) is called *coherent* if each $x \in W$ has a neighborhood U and a monoid P with a map from the constant sheaf of monoids $P \rightarrow \mathcal{M}_U$ such that the pre-log structure associated to the composition $P \rightarrow \mathcal{M}_U \rightarrow \mathcal{O}_U$ coincides with the log structure \mathcal{M}_U . The data $P \rightarrow \mathcal{M}_U$ is called a *chart* of the log structure on U .

For a coherent log structure, we carry over properties of monoids. For example, we call a coherent log structure *fine* if there exists an open cover $\{U_i\}$ by charts $P_i \rightarrow U_i$ with P_i fine monoids.

If $\sigma \subseteq M_{\mathbb{R}}$ is a rational polyhedral cone then the single chart

$$M \cap \sigma \rightarrow \mathbb{C}[M \cap \sigma]$$

determines a coherent log structure on the affine toric variety $\text{Spec}(\mathbb{C}[M \cap \sigma])$. If W is any toric variety, these assemble to natural log structure on W with charts induced by the canonical maps $\sigma \rightarrow \mathbb{C}[M \cap \sigma]$ for each toric open set $\text{Spec} \mathbb{C}[M \cap \sigma]$ of W . These log structures are fine and saturated. For more see [Ka96, Example 2.6].

Example 4.5. The affine line $\mathbb{A}^1 = \text{Spec}(\mathbb{C}[t])$ has a toric log structure whose chart $\mathbb{Z}_{\geq 0} \rightarrow \mathbb{C}[t]$ is given by $k \mapsto t^k$. If $\mathcal{M}_{\mathbb{A}^1}$ denotes the sheaf of monoids and $U \subseteq \mathbb{A}^1$ is an analytic open subset, then

$$\Gamma(U, \mathcal{M}_{\mathbb{A}^1}) = \begin{cases} \Gamma(U, \mathcal{O}^{an,*}) & \text{if } U \text{ does not contain } 0 \\ \mathbb{Z}_{\geq 0} \oplus \Gamma(U, \mathcal{O}^{an,*}) & \text{if } U \text{ does contain } 0 \end{cases}$$

4.1.2. *The log structure on a hypersurface.*

Definition 4.6. If $u : X \rightarrow Y$ is a map of analytic spaces and \mathcal{M}_Y is a log structure on Y , the *pullback log structure* is defined as the associated log structure to the pre-log structure given by the composition $u^{-1}\mathcal{M}_Y \rightarrow f^{-1}\mathcal{O}_Y \rightarrow \mathcal{O}_X$.

If W is a toric variety and $Z \subseteq W$ is a hypersurface, we may pull back the log structure of Section 4.1.1 along the inclusion map $Z \hookrightarrow W$. The charts of the log structure are of the form

$$M \cap \sigma \rightarrow \mathbb{C}[M \cap \sigma] \rightarrow \mathbb{C}[M \cap \sigma]/f$$

if $f = 0$ is the local equation of Z in the chart $\text{Spec}(\mathbb{C}[M \cap \sigma]) \subseteq W$.

Example 4.7. If $(\mathbb{A}^1, \mathcal{M}_{\mathbb{A}^1})$ is the log affine line of Example 4.5 and $0 : \text{Spec} \mathbb{C} \rightarrow \mathbb{A}^1$ is the origin, then the induced log structure on $\text{Spec} \mathbb{C}$ is given by the chart $\mathbb{Z}_{\geq 0} \rightarrow \mathbb{C}$ that carries each $k > 0$ to 0. This is the *standard log point* of [Ka96, Definition 4.3]. We denote it by $\text{Spec} \mathbb{C}^\dagger$. The monoid is $\mathbb{Z}_{\geq 0} \oplus \mathbb{C}^*$.

4.1.3. Log smoothness. A map of log spaces is called *smooth* if it satisfies a lifting criterion for log first order thickenings. A log space is smooth if the projection to a point with trivial log structure is smooth. We do not recall the precise definitions here, see [Ka96, Section 3]. A standard argument shows that many of the varieties and maps of Section 2 are log smooth. We record the facts here.

Let $\Gamma_{\geq h}$ and $Y = \operatorname{Spec}(\mathbb{C}[\widetilde{M} \cap \Gamma_{\geq h}])$ be as in Sections 2.1.1 and 2.1.2, and let $t : Y \rightarrow \mathbb{A}^1$ be the degeneration of Proposition 2.5. Let $X \subseteq Y$ be the hypersurface of Section 2.2. We endow Y with the log structure of Section 4.1.1 which we denote by \mathcal{M}_Y , \mathbb{A}^1 with the log structure of Example 4.5 which we denote by $\mathcal{M}_{\mathbb{A}^1}$, and X with the log structure of Section 4.1.2 which we denote by \mathcal{M}_X .

The map $t : Y \rightarrow \mathbb{A}^1$ upgrades to a map of log structures $t^\dagger : (Y, \mathcal{M}_Y) \rightarrow (\mathbb{A}^1, \mathcal{M}_{\mathbb{A}^1})$ in a unique way. We abuse notation and also use t^\dagger for the restriction $(X, \mathcal{M}_X) \rightarrow (\mathbb{A}^1, \mathcal{M}_{\mathbb{A}^1})$.

Lemma 4.8. *The map $t^\dagger : (X, \mathcal{M}_X) \rightarrow (\mathbb{A}^1, \mathcal{M}_{\mathbb{A}^1})$ is log smooth.*

Let \overline{Y} and \overline{X} be as in Section 2.3 and let \overline{X} , and furnish them with the log structures of Section 4.1.1 and 4.1.2. We denote the log structure on \overline{Y} by $\mathcal{M}_{\overline{Y}}$ and the log structure on \overline{X} by $\mathcal{M}_{\overline{X}}$. The maps \bar{t} of Section 2.3 upgrade to maps of log spaces $(\overline{Y}, \mathcal{M}_{\overline{Y}}) \rightarrow (\mathbb{A}^1, \mathcal{M}_{\mathbb{A}^1})$ and $(\overline{X}, \mathcal{M}_{\overline{X}}) \rightarrow (\mathbb{A}^1, \mathcal{M}_{\mathbb{A}^1})$. We again abuse notation and denote both of these maps by \bar{t}^\dagger .

Lemma 4.9. *The map $\bar{t}^\dagger : (\overline{X}, \mathcal{M}_{\overline{X}}) \rightarrow (\mathbb{A}^1, \mathcal{M}_{\mathbb{A}^1})$ is log smooth.*

Let \mathcal{M}_{X_0} denote the log structure on X_0 induced by \mathcal{M}_X under the inclusion map $X_0 \hookrightarrow X$. Let $\mathcal{M}_{\overline{X}_0}$ denote the log structure on \overline{X}_0 induced by $\mathcal{M}_{\overline{X}}$ under the inclusion map $\overline{X}_0 \hookrightarrow \overline{X}$. Then we have Cartesian diagrams of log spaces

$$\begin{array}{ccc} (\overline{X}_0, \mathcal{M}_{\overline{X}_0}) & \longrightarrow & (\overline{X}, \mathcal{M}_{\overline{X}}) \\ \downarrow & & \downarrow \\ (\operatorname{Spec} \mathbb{C}^\dagger, \mathcal{M}_{\operatorname{Spec} \mathbb{C}^\dagger}) & \longrightarrow & (\mathbb{A}^1, \mathcal{M}_{\mathbb{A}^1}) \end{array} \quad \begin{array}{ccc} (X_0, \mathcal{M}_{X_0}) & \longrightarrow & (X, \mathcal{M}_X) \\ \downarrow & & \downarrow \\ (\operatorname{Spec} \mathbb{C}^\dagger, \mathcal{M}_{\operatorname{Spec} \mathbb{C}^\dagger}) & \longrightarrow & (\mathbb{A}^1, \mathcal{M}_{\mathbb{A}^1}) \end{array}$$

We denote the maps $\overline{X}_0 \rightarrow \operatorname{Spec} \mathbb{C}^\dagger$ and $X_0 \rightarrow \operatorname{Spec} \mathbb{C}^\dagger$ by $\bar{\pi}_0^\dagger$ and π_0^\dagger respectively. We have a similar map $Y_0 \rightarrow \operatorname{Spec} \mathbb{C}^\dagger$, and sometimes we abuse notation and denote it by π_0^\dagger as well.

Lemma 4.10. *The maps π_0^\dagger and $\bar{\pi}_0^\dagger$ are log smooth.*

Remark 4.11. We do not include the proofs of Lemmas 4.8, 4.9, and 4.10 but note that they follow directly from K. Kato's toroidal characterization of log smoothness, see [Ka96, Theorem 4.1].

4.2. The Kato-Nakayama space.

Definition 4.12. Let $W^\dagger = (W, \mathcal{M}_W, \alpha_W)$ be a log space. Suppose W^\dagger is coherent in the sense of Definition 4.4. The *Kato-Nakayama space* is the space W_{\log} whose underlying point set is

$$W_{\log} = \{(x, h) \mid x \in W, h \in \operatorname{Hom}(\mathcal{M}_{W,x}^{\operatorname{gp}}, S^1), \text{ and } h(f) = \frac{f(x)}{|f(x)|} \text{ for any } f \in \mathcal{O}_{W,x}^\times\}.$$

topologized such that whenever $U \subseteq W$ is an open set and $P \rightarrow \mathcal{O}_U$ is a chart, the embedding

$$U_{\log} \hookrightarrow U \times \operatorname{Hom}(P^{\operatorname{gp}}, S^1) \quad (x, h) \mapsto (x, h|_P)$$

is a homeomorphism onto its image. Let $\rho = \rho_{W^\dagger}$ denote the map $W_{\log} \rightarrow W$ given by $\rho(x, h) = x$.

Remark 4.13. The above definition also makes sense when the log structure is not coherent, see [NO10]. The point set definition is the same and the topology is the weak topology with respect to the functions ρ and $(x, h) \rightarrow h(m)$ for m a local section of \mathcal{M}_W . We will need this more general definition in Section 5.

The map ρ is continuous and surjective, and the construction $W^\dagger \mapsto W_{\log}$ is functorial such that for a morphism $W_1^\dagger \rightarrow W_2^\dagger$, the induced map $W_{1,\log} \rightarrow W_{2,\log}$ is continuous.

Remark 4.14. Define the *K-N log point* $\mathrm{Spec} \mathbb{C}_{KN}^\dagger$ to be the analytic space $\mathrm{Spec} \mathbb{C}$ with the log structure given by $\mathcal{M}_{\mathrm{Spec} \mathbb{C}} = \mathbb{R}_{\geq 0} \times S^1$ and $\alpha_{\mathrm{Spec} \mathbb{C}} : (r, h) \mapsto rh$. Then there is a natural identification of sets

$$W_{\log} = \mathrm{Mor}(\mathrm{Spec} \mathbb{C}_{KN}^\dagger, W^\dagger)$$

Example 4.15. If X carries the trivial log structure, then $X_{\log} = X$.

Example 4.16. Consider the affine line $(\mathbb{A}^1, \mathcal{M}_{\mathbb{A}^1})$ of Example 4.5 and the standard log point $\mathrm{Spec} \mathbb{C}^\dagger$ of Example 4.7. Then $(\mathbb{A}^1)_{\log}$ is homeomorphic to $\mathbb{R}_{\geq 0} \times S^1$, $(\mathrm{Spec} \mathbb{C}^\dagger)_{\log}$ is homeomorphic to S^1 , and the map $\rho : \mathbb{R}_{\geq 0} \times S^1 \rightarrow \mathbb{C}$ is given by $(r, e^{i\theta}) \mapsto re^{i\theta}$. In other words the map $(\mathbb{A}^1)_{\log} \rightarrow \mathbb{A}^1$ is the real oriented blowup of the origin and $(\mathrm{Spec} \mathbb{C}^\dagger)_{\log}$ is the “exceptional circle” of this blowup.

In general when W is a toric variety and is furnished with the log structure of Section 4.1.1, the space W_{\log} can be described in the manner of Proposition 1.6.

Lemma 4.17. *Let P be a fine, saturated monoid and furnish $W = \mathrm{Spec} \mathbb{C}[P]$ with the log structure given by the natural chart $P \rightarrow \mathcal{O}_W$. Then W_{\log} is naturally identified with $\mathrm{Hom}(P, \mathbb{R}_{\geq 0} \times S^1)$. Moreover, under the identification $W \cong \mathrm{Hom}(P, \mathbb{C})$ of Proposition 1.6, the map $\rho : W_{\log} \rightarrow W$ is given by composing with the monoid epimorphism $\mathbb{R}_{\geq 0} \times S^1 \rightarrow \mathbb{C}$.*

Proof. This is [KN99], Ex.(1.2.11): \square

From the description of Definition 4.12 we obtain the following.

Lemma 4.18. *Let (W_1, \mathcal{M}_{W_1}) be a log space, let $W_2 \rightarrow W_1$ be a morphism of complex analytic spaces and let \mathcal{M}_{W_2} be the pullback log structure on W_2 of Definition 4.6. The following diagram of topological spaces is Cartesian*

$$\begin{array}{ccc} W_{2,\log} & \longrightarrow & W_2 \\ \downarrow & & \downarrow \\ W_{1,\log} & \longrightarrow & W_1 \end{array}$$

4.2.1. Y_{\log} and $Y_{0,\log}$. In this Section and in Section 4.2.2, we return to the degeneration of our hypersurface. Here we describe $Y_{0,\log}$, the map $\rho : Y_{0,\log} \rightarrow Y_0$, and its fibers.

Let $\Gamma_{\geq h} \subseteq \widetilde{M}_{\mathbb{R}}$ be the overgraph cone of Section 2.1.1. From Remark 2.4, we can describe Y and Y_0 as spaces of monoid homomorphisms

$$\begin{aligned} Y &= \mathrm{Hom}(\widetilde{M} \cap \Gamma_{\geq h}, \mathbb{C}) \\ Y_0 &= \{\phi \in \mathrm{Hom}(\widetilde{M} \cap \Gamma_{\geq h}, \mathbb{C}) \mid \phi(0, 1) = 0\} \end{aligned}$$

Then by Lemmas 4.17 and 4.18

$$\begin{aligned} Y_{\log} &= \operatorname{Hom}(\widetilde{M} \cap \Gamma_{\geq h}, \mathbb{R}_{\geq 0} \times S^1) \\ Y_{0,\log} &= \{\phi \in \operatorname{Hom}(\widetilde{M} \cap \Gamma_{\geq h}, \mathbb{R}_{\geq 0} \times S^1) \mid \phi(0, 1) \in \{0\} \times S^1\} \end{aligned}$$

- (1) Y_{\log} is the space of monoid homomorphisms $\operatorname{Hom}(\widetilde{M} \cap \Gamma_{\geq h}, \mathbb{R}_{\geq 0} \times S^1)$
- (2) $Y_{0,\log}$ is the inverse image of Y_0 under the map $Y_{\log} \rightarrow Y$. In other words, it is the space of monoid homomorphisms $\phi : \widetilde{M} \cap \Gamma_{\geq h} \rightarrow \mathbb{R}_{\geq 0} \times S^1$ carrying $(0, 1)$ to an element of $\{0\} \times S^1$.

4.2.2. X_{\log} and $X_{0,\log}$. Lemmas 4.17 and 4.18 provide the following description of X_{\log} and $X_{0,\log}$. Let $\Gamma_{\geq h} \subseteq \widetilde{M}_{\mathbb{R}}$ be the overgraph cone of Section 2.1.1. Then

- (1) X_{\log} is the inverse image of $X \subseteq Y$ under the map

$$\operatorname{Hom}(\widetilde{M} \cap \Gamma_{\geq h}, \mathbb{R}_{\geq 0} \times S^1) \rightarrow \operatorname{Hom}(\widetilde{M} \cap \Gamma_{\geq h}, \mathbb{C})$$

induced by $\mathbb{R}_{\geq 0} \times S^1 \rightarrow \mathbb{C}$.

- (2) $X_{0,\log}$ is the inverse image of $X_0 \subseteq Y$ under the map

$$\operatorname{Hom}(\widetilde{M} \cap \Gamma_{\geq h}, \mathbb{R}_{\geq 0} \times S^1) \rightarrow \operatorname{Hom}(\widetilde{M} \cap \Gamma_{\geq h}, \mathbb{C})$$

induced by $\mathbb{R}_{\geq 0} \times S^1 \rightarrow \mathbb{C}$.

The map $t^\dagger : (X, \mathcal{M}_X) \rightarrow (\mathbb{A}^1, \mathcal{M}_{\mathbb{A}^1})$ of Lemma 4.9 induces a map $X_{\log} \rightarrow (\mathbb{A}^1)_{\log}$. For $c \in \mathbb{A}_{\log}^1 \cong \mathbb{R}_{\geq 0} \times S^1$, let $(X_{\log})_c$ denote the fiber of this map above c .

The map π_0^\dagger of Lemma 4.10 induces a map $X_{0,\log} \rightarrow \operatorname{Spec} \mathbb{C}^\dagger$. For $e^{i\theta} \in S^1 \cong \operatorname{Spec} \mathbb{C}^\dagger$, denote the fiber of π_0^\dagger by $(X_{0,\log})_\theta$. Then

- (3) $(X_{0,\log})_\theta$ is subset of $X_{0,\log}$ given by maps $\phi : \widetilde{M} \cap \Gamma_{\geq h} \rightarrow \mathbb{R}_{\geq 0} \times S^1$ that carry $(0, 1) \in \Gamma_{\geq h}$ to $(0, e^{i\theta}) \in \mathbb{R}_{\geq 0} \times S^1$.

The restriction of the map $\rho : X_{0,\log} \rightarrow X_0$ to any $(X_{0,\log})_\theta$ is surjective.

The map $\bar{\pi}_Y^\dagger$ (resp. $\bar{\pi}_0^\dagger$) induces a map of Kato-Nakayama spaces

$$(\bar{\pi}_Y)_{\log} : \bar{Y}_{\log} \rightarrow \mathbb{A}_{\log}^1 \quad (\text{resp. } \bar{\pi}_{\log} : \bar{X}_{\log} \rightarrow \mathbb{A}_{\log}^1, \quad \bar{\pi}_{0,\log} : \bar{X}_{0,\log} \rightarrow 0_{\log}).$$

Note that $\bar{X}_{0,\log}$ maps to $S^1 = \operatorname{Hom}(\mathbb{Z}_{\geq 0}, S^1) = 0_{\log}$. We denote the restrictions of these maps to the loci inside $Y \subseteq \bar{Y}$ by removing the bar, e.g., $\pi_{\log} : X_{\log} \rightarrow \mathbb{A}_{\log}^1$. For $c \in \mathbb{A}_{\log}^1$ (resp. 0_{\log}), we denote $(\bar{X}_{\log})_c := \bar{\pi}_{\log}^{-1}(c)$, $(X_{0,\log})_c := \pi_{0,\log}^{-1}(c)$, etc. The fiber of $\pi_{0,\log}$ over $\theta \in S^1$ is given by

$$(X_{0,\log})_\theta = \{\phi \in \operatorname{Hom}(P_\Gamma, \mathbb{R}_{\geq 0} \times S^1) \mid \phi(0, 1) = (0, \theta)\} \times_Y X_0$$

which surjects to X_0 under ρ for each θ .

4.3. Embedding the skeleton into the Kato-Nakayama space. In this section we construct an embedding of the skeleton $S_{\Delta, \mathcal{T}} \subseteq \partial\Delta' \times \operatorname{Hom}(M, S^1)$ (Definition 3.1) into the Kato-Nakayama space of the degeneration $(X_{0,\log})_\theta$ (Section 4.2.2). We will first define a map

$$\lambda : \partial\Delta' \times \operatorname{Hom}(M, S^1) \rightarrow Y_{\log}$$

and the show that λ restricts to an embedding $S_{\Delta, \mathcal{T}} \hookrightarrow (X_{0, \log})_1$. We use the description of Y_{\log} given in Section 4.2.1, i.e.

$$\begin{aligned} Y_{\log} &= \text{Hom}(\widetilde{M} \cap \Gamma_{\geq h}, \mathbb{R}_{\geq 0} \times S^1) \\ &= \text{Hom}(\widetilde{M} \cap \Gamma_{\geq h}, \mathbb{R}_{\geq 0}) \times \text{Hom}(\widetilde{M} \cap \Gamma_{\geq h}, S^1). \end{aligned}$$

Definition 4.19. Let $j : \widehat{\partial\Delta'} \hookrightarrow X_0$ be the embedding of Proposition 3.19, and let us regard $\partial\Delta'$ as a subset of $\widehat{\partial\Delta'}$ by the embedding of Remark 3.10. Define $\lambda : \partial\Delta' \times \text{Hom}(M, S^1) \rightarrow Y_{\log}$ by the formula

$$\lambda(x, \phi)(m, r) = (j(x)(m, r), \phi(m)) \in \mathbb{R}_{\geq 0} \times S^1$$

Remark 4.20. In the Definition, we are regarding $j(x)$ as a homomorphism $\widetilde{M} \cap \Gamma_{\geq h} \rightarrow \mathbb{C}$ in the manner of Proposition 1.6. Proposition 3.17 shows that $j_{\tau, 1}$ maps τ homeomorphically onto $(X_{0, \tau})_{\geq 0}$ so in fact $j(x)$ is a homomorphism $\widetilde{M} \cap \Gamma_{\geq h} \rightarrow \mathbb{R}_{\geq 0}$. The monoid homomorphism $j(x)$ has a messy explicit formula. It is given implicitly by the following rules

- $j(x)(m, r) = 0$ unless $r = h(m)$ and $m \in \mathbb{R}_{\geq 0}\tau_x$
- For $m \in \tau_x^{[0]}$, the values $j(x)(m, h(m))$ are the unique positive real solutions to the following system of equations:

$$(4.1) \quad \sum_{m \in \tau^{[0]}} (j(x)(m, h(m)))^2 m = x \sum_{m \in \tau^{[0]}} (j(x)(m, h(m)))^2$$

$$(4.2) \quad \sum_{m \in \tau^{[0]}} a_m j(x)(m, h(m)) = -a_0$$

The first equation comes from Proposition 3.13.

4.3.1. Properties of the embedding λ .

Proposition 4.21. *The image of $\partial\Delta' \times \text{Hom}(M, S^1)$ under λ is contained in $(Y_{0, \log})_1$. The image of $S_{\Delta, \mathcal{T}}$ under λ is contained in $X_{0, \log}$.*

Proof. By Definition 4.19 and Remark 4.20, for any $x \in \partial\Delta'$ the homomorphism $j(x)$ carries $(0, 1) \in \Gamma_{\geq h}$ to $0 \in \mathbb{R}_{\geq 0}$. From Definition 4.19, the homomorphism $\lambda(x)$ carries $(0, 1)$ to $(0, 1) \in \mathbb{R}_{\geq 0} \times S^1$. It follows that $\lambda(\partial\Delta' \times \text{Hom}(M, S^1)) \subseteq (Y_{0, \log})_1$.

The map $\lambda(x, \phi) : \widetilde{M} \cap \Gamma_{\geq h} \rightarrow \mathbb{R}_{\geq 0} \times S^1$ belongs to $(X_{0, \log})_1 \subseteq (Y_{0, \log})_1$ if and only if

$$(4.3) \quad \sum_{m \in \mathcal{T}^{[0]}} a_m j(x)(m, h(m)) \cdot \phi(m) = -a_0$$

Since (Remark 4.20) $j(x)(m, h(m)) = 0$ unless m belongs to τ_x , the left hand side of (4.3) is

$$\sum_{m \in \tau_x^{[0]}} a_m j(x)(m, h(m)) \phi(m)$$

If (x, ϕ) belongs to $S_{\Delta, \mathcal{T}}$, then $\phi(m) = 1$ for every $m \in \tau_x^{[0]}$, so that this is equal to $-a_0$ by Remark 4.20. □

Proposition 4.22. *For each $d \in D_\tau$, let $dA_\tau \subseteq G_\tau$ denote the corresponding coset of A_τ (see Eq. 3.1). Let $r : \text{Hom}(\widetilde{M}, S^1) \rightarrow \text{Hom}(M, S^1)$ denote the restriction map induced by the inclusion $m \mapsto (m, 0)$. Then r induces an isomorphism the set of homomorphisms $\psi : \widetilde{M} \rightarrow S^1$ obeying the conditions*

- (1) $\psi(m, h(m)) = d(m)$ for $m \in \tau$
- (2) $\psi(0, 1) = 1$

to a coset of A_τ . is isomorphic to a coset of A_τ in G_τ (see Eq. 3.1) via the restriction map $\psi \mapsto \phi : M \rightarrow S^1$, $\phi(m) = \psi(m, 0)$.

Proof. Because of the second condition, ψ is determined by its values on $M \cong M \times \{0\} \subseteq \widetilde{M}$. If ψ and ψ' obey both conditions, then $\psi/\psi' = 1$ on τ , which characterizes A_τ . \square

Theorem 4.23. *Let j be the map of Proposition 3.19, let λ be the map of Definition 4.19, and let ρ_1 be the map of Definition 4.12. Then the square*

$$\begin{array}{ccc} S_{\Delta, \tau} & \xrightarrow{\lambda} & (X_{0, \log})_1 \\ \downarrow & & \downarrow \rho_1 \\ \widehat{\partial\Delta'} & \xrightarrow{j} & X_0 \end{array}$$

is Cartesian. In particular, $\lambda|_{S_{\Delta, \tau}} : S_{\Delta, \tau} \rightarrow (X_{0, \log})_1$ is a closed embedding.

Proof. Fix $(x, d) \in \widehat{\partial\Delta'}$. Thus, $x \in \partial\Delta'$ and d is a homomorphism $M \cap \mathbb{R}_{\geq 0}\tau_x \rightarrow S^1$ carrying the vertices of τ_x to 1. If we regard $j(x)$ as a monoid homomorphism as in Remark 4.20, then $j(x, d)$ is the monoid homomorphism

$$j(x, d)(m, k) = \begin{cases} d(m)j(x)(m, k) & \text{if } k = h(m) \text{ and } m \in \mathbb{R}_{\geq 0}\tau_x \\ 0 & \text{otherwise} \end{cases}$$

The fiber of the left vertical map above (x, d) is a coset of A_τ in G_τ . We will show that λ carries this homeomorphically onto the fiber of ρ_1 above $j(x, d)$.

Let $r : \widetilde{M} \cap \Gamma_{\geq h} \rightarrow \mathbb{R}_{\geq 0}$ and $\psi : \widetilde{M} \cap \Gamma_{\geq h} \rightarrow S^1$ be the components of a point $(r, \psi) \in (X_{0, \log})_1 \subseteq Y_{\log}$.

Claim: The point (r, ψ) belongs to $\rho_1^{-1}(j(x, d))$ if and only if

- $r(m, k) = 0$ unless $k = h(m)$ and $m \in \mathbb{R}_{\geq 0}\tau_x$
- $r(m, h(m)) = j(x)(m, h(m))$ when $m \in \mathbb{R}_{\geq 0}\tau_x$
- $\psi(m, h(m)) = d(m)$ when $m \in \tau_x$ and (because we have restricted ρ to $(X_{0, \log})_1$) $\psi(0, 1) = 1$.

Because of the claim, the fiber $\rho_1^{-1}(j(x, d))$ is naturally parameterized by the set of homomorphisms $\psi : \widetilde{M} \rightarrow S^1$ that obey the third condition on this list, which is a coset of A_τ in G_τ by Proposition 4.22. This agrees with the preimage in $S_{\Delta, \tau}$ of (x, d) under λ .

To prove the claim, note that by definition the point $\rho_1(r, \psi) = j(x, d)$ if and only if the following holds: for all $(m, k) \in \widetilde{M} \cap \Gamma_{\geq h}$,

$$r(m, k)\psi(m, k) = \begin{cases} d(m)j(x)(m, k) & \text{if } k = h(m) \text{ and } m \in \mathbb{R}_{\geq 0}\tau \\ 0 & \text{otherwise} \end{cases}$$

In particular we must have $r(m, k) = 0$ unless $k = h(m)$, and

$$r(m, h(m)) = \psi(m, h(m))^{-1} d(m) j(x)(m, h(m))$$

Since $r(m, h(m))$ and $j(x)(m, k)$ are positive real numbers, we must have $\psi(m, h(m)) = d(m)$. \square

Since from the above proof we see that if $\dim \tau_x = n$, then $\rho_1^{-1}(j(x, d)) = A_{\tau_x} = 1$, we have the following corollary.

Corollary 4.24. *Let $(x, d) \in \widehat{\partial \Delta'}$ and suppose $\dim(\tau_x) = n$. Then, in a neighborhood of $j(x, d)$, X_0 is smooth and ρ_1 is an isomorphism.*

4.4. $S_{\Delta, \mathcal{T}}$ is a strong deformation retract. In this section we prove that $S_{\Delta, \mathcal{T}}$ embeds in $(X_{0, \log})_1$ as a strong deformation retract. Recall that Proposition 3.19 and Theorem 3.27, together with Remark 3.15, give the following diagram,

$$\begin{array}{ccccc} S_{\Delta, \mathcal{T}} & \xrightarrow{\lambda} & (X_{0, \log})_1 & & \\ \downarrow & & \downarrow \rho_1 & \searrow \nu \circ \rho_1 & \\ \widehat{\partial \Delta'} & \xrightarrow{j} & X_0 & \xrightarrow{\nu} & \partial \Delta'. \end{array}$$

- Lemma 4.25.** (1) *Let $\tau \in \mathcal{T}$, then $X_{0, \tau}$ retracts onto $p_{\tau}^{-1}(\mathbb{P}_{\geq 0}^{\dim(\tau)}) \cup \nu_{\tau}^{-1}(\partial \tau)$.¹*
 (2) *If $k \leq n$, then $\cup_{\dim(\tau)=k} X_{0, \tau}$ retracts onto $\cup_{\dim(\tau)=k} (p_{\tau}^{-1}(\mathbb{P}_{\geq 0}^{\dim(\tau)}) \cup \nu_{\tau}^{-1}(\partial \tau))$.*
 (3) *If $k \leq n$, $\widehat{\partial \Delta'} \cup (\cup_{\dim(\tau)=k} X_{0, \tau})$ retracts onto $\widehat{\partial \Delta'} \cup (\cup_{\dim(\tau)=k} \nu_{\tau}^{-1}(\partial \tau))$.*

Proof. Note that $\mathbb{P}_{\geq 0}^{\dim(\tau)} \cup \mu^{-1}(\partial \tau)$ embeds in $\mathbb{P}^{\dim(\tau)} \setminus V(l_{\tau})$ as a deformation retract. This can be seen as follows. We can write $\mu^{-1}(\partial \tau)$ as the union $\cup_{\tau' \subsetneq \tau} \mathbb{P}^{\dim(\tau')} \setminus V(l_{\tau'})$. Proposition 3.26 implies that for all $\tau' \subsetneq \tau$, $\mathbb{P}^{\dim(\tau')} \setminus V(l_{\tau'})$ retracts onto $\mathbb{P}_{\geq 0}^{\dim(\tau')} \subseteq \mathbb{P}_{\geq 0}^{\dim(\tau)}$, in a way that is compatible with the inclusions of smaller strata. This gives a retraction $\mu^{-1}(\partial \tau) \rightarrow \partial(\mathbb{P}_{\geq 0}^{\dim(\tau)})$, that can be extended to a retraction $\mathbb{P}_{\geq 0}^{\dim(\tau)} \cup \mu^{-1}(\partial \tau) \rightarrow \mathbb{P}_{\geq 0}^{\dim(\tau)}$, by defining it to be the identity on $\mathbb{P}_{\geq 0}^{\dim(\tau)}$.

Since $\mathbb{P}_{\geq 0}^{\dim(\tau)}$ is contractible, this implies that $\mathbb{P}_{\geq 0}^{\dim(\tau)} \cup \mu^{-1}(\partial \tau)$ is contractible as well. The existence of a retraction $\mathbb{P}^{\dim(\tau)} \setminus V(l_{\tau}) \rightarrow \mathbb{P}_{\geq 0}^{\dim(\tau)} \cup \mu^{-1}(\partial \tau)$ is then a consequence of standard facts about CW complexes: any contractible subcomplex of a contractible CW complex is a strong deformation retract, see e.g. [Mc] Lemma 1.6. Claim (1) can be proved by applying Lemma 3.24 to p_{τ} . In fact, by Proposition 2.16, $p_{\tau} : X_{0, \tau} \rightarrow \mathbb{P}^{\dim(\tau)} \setminus V(l_{\tau})$ is unramified away from $\mathbb{P}_{\geq 0}^{\dim(\tau)} \cup \mu^{-1}(\partial \tau)$.

We turn now to claim (2). Note that for any pair of distinct k -dimensional simplices τ_1, τ_2 , $X_{0, \tau_1} \cap X_{0, \tau_2} = \nu_{\tau_1}^{-1}(\partial \tau_1) \cap \nu_{\tau_2}^{-1}(\partial \tau_2)$. As a consequence, the retractions defined in (1) agree on the intersections of the various components: in fact, they restrict to the identity there. This guarantees that they assemble to give a retraction of $\cup_{\dim(\tau)=k} X_{0, \tau}$ onto

¹The statement of Lemma 4.25 is very related to Theorem 3.27, but does not follow directly from it: recall that the target of the retraction in Theorem 3.27 is $p_{\tau}^{-1}(\mathbb{P}_{\geq 0}^{\dim(\tau)})$.

$\bigcup_{\dim(\tau)=k} (p_\tau^{-1}(\mathbb{P}_{\geq 0}^{\dim(\tau)}) \cup (\mu_\tau \circ p_\tau)^{-1}(\partial\tau))$, as desired. The last claim follows from the observation that $\widehat{\partial\Delta'} \cap (\bigcup_{\dim(\tau)=k} X_{0,\tau})$ is contained in $\bigcup_{\dim(\tau)=k} (p_\tau^{-1}(\mathbb{P}_{\geq 0}^{\dim(\tau)}) \cup (\nu_\tau)^{-1}(\partial\tau))$. Thus, the retraction obtained in (2) can be extended to $\widehat{\partial\Delta'} \cup (\bigcup_{\dim(\tau)=k} X_{0,\tau})$, by setting it equal to the identity on $\widehat{\partial\Delta'}$. \square

Theorem 4.26. $S_{\Delta,\mathcal{T}}$ embeds in $(X_{0,\log})_1$ as a strong deformation retract.

Proof. Let $\partial\Delta'_k$ be the $(n-k)$ -skeleton of the stratification of $\partial\Delta'$ given by \mathcal{T} , i.e. set $\partial\Delta'_k := \sqcup_{\tau \in \mathcal{T}, \dim \tau \leq n-k} \tau^\circ$. Note that $\nu^{-1}(\partial\Delta'_k) = \bigcup_{\dim(\tau)=n-k} X_{0,\tau}$. Applying Lemma 4.25 (3), with k equal to n , we obtain a retraction of X_0 onto $\widehat{\partial\Delta'} \cup \nu^{-1}(\partial\Delta'_1)$. By Corollary 4.24, ρ_1 is a homeomorphism over $X_0 - \nu^{-1}(\partial\Delta'_1)$, and thus in particular over $X_0 - (\widehat{\partial\Delta'} \cup \nu^{-1}(\partial\Delta'_1))$. Lemma 3.24 then implies that $\rho_1^{-1}(\widehat{\partial\Delta'} \cup \nu^{-1}(\partial\Delta'_1)) = S_{\Delta,\mathcal{T}} \cup (\nu \circ \rho_1)^{-1}(\partial\Delta'_1)$ embeds in $(X_{0,\log})_1$ as a deformation retract.

By Lemma 4.25 (2), $\nu^{-1}(\partial\Delta'_1)$ retracts onto $(\bigcup_{\dim(\tau)=n-1} p_\tau^{-1}(\mathbb{P}_{\geq 0}^{\dim(\tau)})) \cup \nu^{-1}(\partial\Delta'_2)$. Also, for all τ , ρ_1 restricts to a principal A_τ -bundle over $\nu^{-1}(\tau^\circ)$ (see the proof of Theorem 4.23). Thus we can apply Lemma 3.24 in the following way: using the notations of Lemma 3.24, set $W_1 = (\nu \circ \rho_1)^{-1}(\partial\Delta'_1)$, $p = \rho_1$ (restricted to W_1), and $K_2 = (\bigcup_{\dim(\tau)=n-1} p_\tau^{-1}(\mathbb{P}_{\geq 0}^{\dim(\tau)})) \cup \nu^{-1}(\partial\Delta'_2)$. This gives a retraction of $(\nu \circ \rho_1)^{-1}(\partial\Delta'_1)$ onto $(\bigcup_{\dim(\tau)=n-1} (p_\tau \circ \rho_1)^{-1}(\mathbb{P}_{\geq 0}^{\dim(\tau)})) \cup (\nu \circ \rho_1)^{-1}(\partial\Delta'_2)$.

Note that $S_{\Delta,\mathcal{T}} \cap (\nu \circ \rho_1)^{-1}(\partial\Delta'_1) \subseteq (\bigcup_{\dim(\tau)=n-1} (p_\tau \circ \rho_1)^{-1}(\mathbb{P}_{\geq 0}^{\dim(\tau)})) \cup (\nu \circ \rho_1)^{-1}(\partial\Delta'_2)$. This follows from the proof of Lemma 4.25 (3), observing that $S_{\Delta,\mathcal{T}} = \rho_1^{-1}(\widehat{\partial\Delta'})$, while $(\nu \circ \rho_1)^{-1}(\partial\Delta'_1) = \rho_1^{-1}(\bigcup_{\dim(\tau)=n-1} X_{0,\tau})$. Thus, in the usual manner, we extend the retraction constructed in the previous paragraph to a retraction of $S_{\Delta,\mathcal{T}} \cup (\nu \circ \rho_1)^{-1}(\partial\Delta'_1)$ onto $S_{\Delta,\mathcal{T}} \cup (\nu \circ \rho_1)^{-1}(\partial\Delta'_2)$, by setting it equal to the identity on $S_{\Delta,\mathcal{T}}$. Iterating this argument, by considering the preimage along $\nu \circ \rho_1$ of skeleta of the stratification of $\partial\Delta'$ of increasingly higher codimension, in n steps we achieve a retraction of $(X_{0,\log})_1$ onto $S_{\Delta,\mathcal{T}}$. \square

4.5. Proof of Main Theorem (1.2). We wish to relate the affine hypersurface $Z \cong X_1$ to the special fiber of the Kato-Nakayama space $(X_{0,\log})_1$. In fact these spaces are homeomorphic, as we now show by proving that Kato-Nakayama space is a fiber bundle. Together with Theorem 4.26, this establishes the Main Theorem (1.2) of the introduction.

We wish to show that the map $X_{\log} \rightarrow \mathbb{R}_{\geq 0} \times S^1$ is a topological fiber bundle. It is easy to see that it is a submersion, but since it is not proper one cannot directly conclude that it is locally trivial. However the relative compactification $\overline{X} \rightarrow \mathbb{C}$ considered in Section 2.3 admits a natural log structure, and the map $\overline{X}_{\log} \rightarrow \mathbb{R}_{\geq 0} \times S^1$ is proper. We will show that this map is a fiber bundle whose fibers are manifolds with boundary, by appealing to a theorem of Nakayama and Ogus:

Theorem 4.27 (Nakayama-Ogus). *Let W^\dagger be a fine log space, let $(\mathbb{A}^1)^\dagger$ be the affine line with the log structure of Example 4.5, and let $f : W^\dagger \rightarrow (\mathbb{A}^1)^\dagger$ be a morphism of fine log spaces. If f is proper, separated, and smooth, then the map $f_{\log} : W_{\log} \rightarrow \mathbb{R}_{\geq 0} \times S^1$ is a topological fiber bundle.*

Proof. By [NO10, Remark 2.2], any map f satisfying the hypotheses of the Theorem is exact in the sense of loc. cit., Definition 2.1. Then the Theorem is a special case of loc. cit. Theorem 5.1. \square

Recall that an n -dimensional topological manifold with boundary is a topological space locally homeomorphic to either \mathbb{R}^n or $\mathbb{R}^{n-1} \times \mathbb{R}_{\geq 0}$. If W is a topological manifold with boundary write W° for the interior, i.e. the set of points with a neighborhood homeomorphic to \mathbb{R}^n , and ∂W for the complement of W° .

Proposition 4.28. (1) \overline{X}_{\log} as well as $(\overline{X}_{\log})_c$ for each $c \in \mathbb{A}_{\log}^1$ is a topological manifold with boundary.

(2) For each $c \in \mathbb{R}_{\geq 0} \times S^1$, the interior of $(\overline{X}_{\log})_c$ is precisely $(X_{\log})_c$.

Proof. Recall that in [NO10], a morphism of monoids $\theta : P \rightarrow Q$ is called *vertical* if the image of P is not contained in any proper face of Q . The morphism is *exact* if the diagram

$$\begin{array}{ccc} P & \longrightarrow & Q \\ \downarrow & & \downarrow \\ P^{\text{gp}} & \longrightarrow & Q^{\text{gp}} \end{array}$$

is Cartesian. A morphism $(W_1, \mathcal{M}_1) \rightarrow (W_2, \mathcal{M}_2)$ of log spaces is called *vertical at $x \in W_1$* (resp. *exact at $x \in W_1$*) if the induced map of monoids $\mathcal{M}_{2,f(x)} \rightarrow \mathcal{M}_{1,x}$ is vertical (resp. exact). We have log smoothness of the maps in consideration by Lemmata 4.8 and 4.9. Moreover, it is not hard to see that the maps are exact. Therefore, by means of [NO10, Theorem 3.5], the Proposition is a consequence of the following claim:

A point of \overline{X} is vertical for the map $\overline{\pi}^\dagger$ if and only if it belongs to $X \subseteq \overline{X}$.

Indeed, recalling that $\mathbb{Z}_{\geq 0}$ gives a chart on the base, we just need to check where a generator of $\mathbb{Z}_{\geq 0}$ gets mapped into a proper face a stalk of the log structures upstairs and this is precisely in $\overline{X} \setminus X$. □

Corollary 4.29. The map $\overline{\pi}_{\log} : \overline{X}_{\log} \rightarrow \mathbb{A}_{\log}^1$ is a topological fiber bundle, i.e., each point in the base has a neighborhood U such that $\overline{\pi}_{\log}$ restricted to $\overline{f}_{\log}^{-1}(U)$ is homeomorphic to the second projection from the product $F \times U \rightarrow U$ where F is homeomorphic to a fiber of $\overline{\pi}_{\log}$.

Proof. Both \overline{X}^\dagger , $(\mathbb{A}^1)^\dagger$ are fine log spaces. The map $\overline{\pi}$ is proper, separated and exact by Theorem 4.27. Log smoothness is given by Lemma 4.10. □

Corollary 4.30. The map $\pi_{\log} : X_{\log} \rightarrow \mathbb{A}_{\log}^1$ is a topological fiber bundle.

In particular, $(X_{0,\log})_1$ is homeomorphic to the hypersurface $Z = V(f)$. By Theorem 4.26, $(X_{0,\log})_1$ deformation retracts to $S_{\Delta,\tau}$. Therefore, so does Z . We have thus proven the Main Theorem (1.2) of the introduction.

5. THE GENERAL CASE

We now consider a generalization of our setting and our theorem to address the case where $Z = f^{-1}(0)$ is a smooth hypersurface in a general affine toric variety A . In this section, we give a skeleton for Z , as before depending on a regular triangulation of Δ , the Newton polytope of f . This skeleton will be a topological quotient space of the skeleton constructed in Sections 2–4 for the intersection of Z with the open torus in A .

Example 5.1. Consider $A = \mathbb{C}^2$ and $f : \mathbb{C}^2 \rightarrow \mathbb{C}$, $f(x, y) = -1 + x + y$. Then $\Delta = \text{conv}\{(0, 0), (1, 0), (0, 1)\} \subseteq \mathbb{R}^2$. Note that $0 \in \partial\Delta$. Note that, setting $M = \mathbb{Z}^2$ we have $A = \text{Spec}(\mathbb{C}[K \cap M])$ where $K = \mathbb{R}_{\geq 0}^2 \subseteq \mathbb{R}^2$ is a convex, maximal-dimensional cone. This is an example of the general setting we consider.

5.1. The general setup. Let $M \cong \mathbb{Z}^{n+1}$ be a lattice. Let $M_{\mathbb{R}} := M \otimes_{\mathbb{Z}} \mathbb{R} \cong \mathbb{R}^{n+1}$. Let $K \subseteq M_{\mathbb{R}}$ be an $(n+1)$ -dimensional, convex rational polyhedral cone. Then $M \cap K$ is a finitely generated monoid and $A := \text{Spec}(\mathbb{C}[M \cap K])$ is an affine toric variety. The smallest torus orbit in A is $\text{Spec}(\mathbb{C}[M \cap K^\times])$ where K^\times denotes the maximal linear subspace contained in K . We set $a = \dim K^\times$ and $b = n + 1 - a$. Consider the projection $M \rightarrow M/(M \cap K^\times)$ and its real analog $p_{K^\times} : M_{\mathbb{R}} \rightarrow M_{\mathbb{R}}/K^\times$. We set $\overline{K} = p_{K^\times}(K)$ and have

$$A \cong \text{Spec}(\mathbb{C}[M \cap K^\times]) \times \text{Spec} \mathbb{C}[\overline{K} \cap (M/(M \cap K^\times))]$$

and the first factor is a -dimensional and the second b -dimensional.

Remark 5.2. Note that A is smooth if and only if $(K, M_{\mathbb{R}}, M)$ is isomorphic to $(\mathbb{R}^a \times \mathbb{R}_{\geq 0}^b, \mathbb{R}^{a+b}, \mathbb{Z}^{a+b})$.

Let $f \in \mathbb{C}[M \cap K]$ be a regular function on A , and let Δ be the Newton polytope of f and $Z := f^{-1}(0) \subseteq A$. We make the following assumptions:

Assumptions 5.3. (1) A is either smooth or has at most an isolated singularity. Note that the latter implies that $b = 0$, if A is singular,
 (2) $\dim \Delta = \dim K$,
 (3) $\overline{K} = \mathbb{R}_{\geq 0} p_{K^\times}(\Delta)$, so Δ generates the cone K up to invertible elements,
 (4) Z is smooth, doesn't contain a torus orbit and its intersection with each torus orbit is reduced and smooth.

Remark 5.4. (1) We necessarily have $\Delta \subseteq K$, and Δ contains 0 by assumption (4) above.
 (2) Note that if assumption (2) above is violated then Z splits as a product $Z_1 \times Z_2$ where $\dim Z_1 = \dim \Delta$, Z_1 has the same Newton polytope as Z and Z_2 is isomorphic to $(\mathbb{C}^*)^{a'} \times \mathbb{C}^{b'}$ for suitable a', b' . Since $(S^1)^{a'}$ is a skeleton for $(\mathbb{C}^*)^{a'} \times \mathbb{C}^{b'}$, imposing assumption (2) loses no generality.
 (3) In the case where A is smooth, note that assumption (3) above can always be achieved by a linear coordinate transformation of A .

Example 5.5. Let $M = \mathbb{Z}^{n+1}$. If $K = M_{\mathbb{R}}$, then $A = (\mathbb{C}^*)^{n+1}$. If $a + b = n + 1$ and $K = \mathbb{R}^a \times \mathbb{R}_{\geq 0}^b$, then $A = (\mathbb{C}^*)^a \times \mathbb{C}^b$. For an example of a singular ambient variety, take $n = 1$ and put $K = \{x \geq |y|\} \subseteq \mathbb{R}^2$. Then $A = \mathbb{C}^2/\mathbb{Z}_2$.

As in equation (2.1), we assume that Δ is equipped with a lattice triangulation \mathcal{T}_Δ and that

$$(5.1) \quad f = a_0 + \sum_{m \in \mathcal{T}^{[0]}} a_m z^m.$$

As before, we assume $0 \in \mathcal{T}_\Delta^{[0]}$ and that we have a convex piecewise linear function $h : \mathbb{R}_{\geq 0}\Delta \rightarrow \mathbb{R}$ taking non-negative integral values on M such that the maximal dimensional simplices in \mathcal{T}_Δ coincide with the non-extendable closed domains of linearity of $h|_\Delta$.

5.2. The general definition of the skeleton. As before, let \mathcal{T} denote the subset of \mathcal{T}_Δ of the cells not containing 0. Let $\partial\Delta'$ denote the union of the cells in \mathcal{T} and for $x \in \partial\Delta'$, let τ_x denote the smallest cell of \mathcal{T} containing x . Recall $S_{\Delta,\mathcal{T}}$ from Definition 3.1

$$S_{\Delta,\mathcal{T}} = \{(x, \phi) \in \partial\Delta' \times \text{Hom}(M, S^1) \mid \phi(v) = 1 \text{ whenever } v \text{ is a vertex of } \tau_x\}.$$

For $x \in K$, we denote by K_x the smallest face of K containing x .

Definition 5.6. Let $S_{\Delta,\mathcal{T},K}$ denote the quotient of $S_{\Delta,\mathcal{T}}$ by the equivalence relation \sim given by

$$(x, \phi) \sim (x', \phi') \iff x = x' \text{ and } \phi|_{K_x \cap M} = \phi'|_{K_x \cap M}$$

The goal is to show that $S_{\Delta,\mathcal{T},K}$ embeds in Z as a deformation retract.

5.3. Construction of the ambient degeneration. The construction of the degeneration in the general case is not different from the previous. For completeness, we repeat it here. Recall the notation $\widetilde{M} = M \oplus \mathbb{Z}$, $\widetilde{M}_{\mathbb{R}} = \widetilde{M} \otimes_{\mathbb{Z}} \mathbb{R}$. As in Section 2.3, we define the non-compact polyhedron

$$\overline{\Gamma} = \{(m, r) \mid m \in \Delta, r \geq h(m)\} \subseteq \widetilde{M}_{\mathbb{R}}$$

and \overline{Y} be the toric variety given by the normal fan of $\overline{\Gamma}$. We may set $\Gamma_{\geq h} = \mathbb{R}_{\geq 0} \overline{\Gamma}$ and find the affine chart

$$Y = \text{Spec } \mathbb{C}[\Gamma_{\geq h} \cap \widetilde{M}]$$

on which we have the two regular functions $t = z^{(0,1)}$ and $\tilde{f} = \sum_{m \in \Delta} a_m z^{(m, h(m))}$. In fact, t extends to a regular function on \overline{Y} . Let $X = V(\tilde{f})$ denote the affine hypersurface cut out by \tilde{f} in Y and let \overline{X} denote its closure in \overline{Y} . We restrict t to a regular function on \overline{X} .

The following lemma elucidates the relation between $\overline{\Gamma}$ and K .

Lemma 5.7. *We have an inclusion preserving bijection*

$$\{\text{faces of } \overline{\Gamma} \text{ containing } \overline{\Gamma} \cap (K^\times \times \mathbb{R})\} \longleftrightarrow \{\text{faces of } K\}$$

by sending a face G on the left hand side to $(G + (K^\times \times \mathbb{R})) \cap M_{\mathbb{R}}$ on the right.

Proof. Faces of K are in inclusion-preserving bijection with faces of $K \times \mathbb{R}$ and the latter coincides with the localization $\overline{\Gamma} + (K^\times \times \mathbb{R})$ of $\overline{\Gamma}$ by Assumptions 5.3, (3). \square

5.4. The non-standard log structure. Let D denote the complement of the open torus in \overline{Y} . Then D is a toric divisor in \overline{Y} . In Section 4, we used the standard toric log structure $\mathcal{M}_{\overline{Y}} = \mathcal{M}_{(\overline{Y}, D)}$ on the toric variety \overline{Y} (Section 4.1.1), which eventually led to an embedding of $S_{\Delta,\mathcal{T}} \subseteq (\overline{Y}_{0,\log})_1$ as a deformation retract. To indicate that \overline{Y}_{\log} is defined using the log structure $\mathcal{M}_{\overline{Y}}$, we denote it from now on by $\overline{Y}(\mathcal{M}_{\overline{Y}})_{\log}$.

We now construct another log structure $\mathcal{F}_{\overline{Y}}$ on \overline{Y} . For this we specify a reduced toric divisor $D_{\mathcal{F}} \subseteq \overline{Y}$, i.e. $D_{\mathcal{F}} \subseteq D$, and we then define $\mathcal{F}_{\overline{Y}}$ as the divisorial log structure with respect to $D_{\mathcal{F}}$. Recall that the components of D correspond to the facets of $\overline{\Gamma}$. To define $D_{\mathcal{F}}$, we need to pick a subset of these facets.

Definition 5.8. We let $D_{\mathcal{F}} \subseteq \overline{Y}$ be the reduced toric divisor whose components correspond to the facets of $\overline{\Gamma}$ that do not contain the face $(K^\times \times \mathbb{R}) \cap \overline{\Gamma}$ and define $\mathcal{F}_{\overline{Y}} = \mathcal{M}_{(\overline{Y}, D_{\mathcal{F}})}$.

We want to describe the stalks of $\mathcal{F}_{\bar{\Gamma}}$ explicitly. Let F_1, \dots, F_r be an enumeration of the facets of $\bar{\Gamma}$ containing $(K^\times \times \mathbb{R}) \cap \bar{\Gamma}$. For a face $G \subseteq \bar{\Gamma}$, we denote by $\langle G, F_i \rangle$, the smallest face of $\bar{\Gamma}$ containing G and F_i , i.e.

$$\langle G, F_i \rangle = \begin{cases} F_i & \text{if } G \subseteq F_i, \\ \bar{\Gamma} & \text{otherwise.} \end{cases}$$

We define $F_G := \bigcap_{i=1}^r \langle G, F_i \rangle$. For faces $G_1, G_2 \subseteq \bar{\Gamma}$ with $G_1 \subseteq G_2$, we have $F_{G_1} \subseteq F_{G_2}$.

Lemma 5.9. *We have $F_G = \bigcap_{G \subseteq F_i} F_i = \langle \bar{\Gamma} \cap K^\times \times \mathbb{R}, G \rangle$*

We can now identify the stalks of $\mathcal{F}_{\bar{\Gamma}}$.

Lemma 5.10. *Let $y \in \bar{Y}$ be a point and $G \subseteq \Gamma$ be the face that corresponds to the torus orbit that contains y . We have*

$$\mathcal{F}_{\bar{Y}, y} = (\widetilde{M} \cap \mathbb{R}_{\geq 0}(F_G - G)) \otimes_{(\widetilde{M} \cap \mathbb{R}_{\geq 0}(F_G - G))^\times} \mathcal{O}_{\bar{Y}, y}^\times$$

and this is a face of

$$\mathcal{M}_{\bar{Y}, y} = (\widetilde{M} \cap \mathbb{R}_{\geq 0}(\bar{\Gamma} - G)) \otimes_{(\widetilde{M} \cap \mathbb{R}_{\geq 0}(\bar{\Gamma} - G))^\times} \mathcal{O}_{\bar{Y}, y}^\times.$$

Proof. On the chart $\widetilde{M} \cap \mathbb{R}_{\geq 0}(\bar{\Gamma} - G) \rightarrow \mathbb{C}[\widetilde{M} \cap \mathbb{R}_{\geq 0}(\bar{\Gamma} - G)]$ of the log structure $\mathcal{M}_{\bar{Y}}$, the subsheaf $\mathcal{F}_{\bar{Y}}$ up to invertible elements is generated by the those monomials that do not vanish on the divisors corresponding to F_1, \dots, F_r , i.e. precisely the monomials contained in $\mathbb{R}_{\geq 0}(F_G - G)$. Moreover, $\mathbb{R}_{\geq 0}(F_G - G)$ is clearly a face of $\mathbb{R}_{\geq 0}(\bar{\Gamma} - G)$. \square

The log structure $\mathcal{F}_{\bar{Y}}$ will in general not be coherent. However we have the following replacement:

Proposition 5.11. *The log structure $\mathcal{F}_{\bar{Y}}$ is relatively coherent in $\mathcal{M}_{\bar{Y}}$ in the sense of [NO10, Def. 3.6, 1.].*

Proof. This just states that $\mathcal{F}_{\bar{Y}}$ is a sheaf of faces in $\mathcal{M}_{\bar{Y}}$ which is Lemma 5.10. \square

Let $\mathcal{F}_{\bar{X}}$ (resp. $\mathcal{M}_{\bar{X}}$) denote the pullback of the log structure $\mathcal{F}_{\bar{Y}}$ (resp. $\mathcal{M}_{\bar{Y}}$) to \bar{X} .

Corollary 5.12. *The log structure $\mathcal{F}_{\bar{X}}$ is relatively coherent in $\mathcal{M}_{\bar{X}}$.*

5.5. Relative log smoothness. Note that $t = z^{(0,1)}$ is a global section of $\mathcal{F}_{\bar{Y}}$ since all F_i contain $(0, 1)$. Thus, by mapping the generator of $\mathbb{Z}_{\geq 0}$ to t , we obtain a map of log spaces $\bar{t}^\dagger : (\bar{Y}, \mathcal{F}_{\bar{Y}}) \rightarrow (\mathbb{A}^1, \mathcal{M}_{\mathbb{A}^1})$. Moreover the inclusion $\mathcal{F}_{\bar{Y}} \subseteq \mathcal{M}_{\bar{Y}}$ induces a map $g^{\bar{Y}}$ so that we have the sequence of maps of log spaces

$$(\bar{Y}, \mathcal{M}_{\bar{Y}}) \xrightarrow{g^{\bar{Y}}} (\bar{Y}, \mathcal{F}_{\bar{Y}}) \xrightarrow{\bar{t}^\dagger} (\mathbb{A}^1, \mathcal{M}_{\mathbb{A}^1})$$

and we know that the composition $g^{\bar{Y}} \circ \bar{t}^\dagger$ is log smooth by a variant of Lemma 4.9 for \bar{Y} . Recall from [NO10, Def. 3.6, 2.] the definition of a relatively log smooth map.

Lemma 5.13. *If A is smooth, then the map \bar{t}^\dagger is relatively log smooth. If A is not smooth, then \bar{t}^\dagger is relatively log smooth away from the closure of the torus orbit in \bar{Y} corresponding to $(0 \times \mathbb{R}) \cap \bar{\Gamma}$.*

Proof. It remains to show that the stalks of $\mathcal{M}_{\bar{Y}}/\mathcal{F}_{\bar{Y}}$ are free monoids at points for which we claim the map to be relatively log smooth. Let $y \in \bar{Y}$ be a point in a torus orbit corresponding to a face $G \subseteq \bar{\Gamma}$. By Lemma 5.10, we have $\mathcal{M}_{\bar{Y},y}/\mathcal{F}_{\bar{Y},y} = (\widetilde{M} \cap \mathbb{R}_{\geq 0}(\bar{\Gamma} - G)) / (\widetilde{M} \cap \mathbb{R}_{\geq 0}(F_G - G))$ and we need to show that this is isomorphic to $\mathbb{Z}_{\geq 0}^s$ for some s . This is equivalent with saying that \bar{Y} is smooth in a neighborhood of the torus orbit corresponding to the smallest face of $\bar{\Gamma}$ that contains F_G and G . It suffices to show that for any subset $I \subseteq \{1, \dots, r\}$, Y is smooth in a neighborhood of the torus orbit corresponding to $F_I := \Gamma_{\geq h} \cap \bigcap_{i \in I} F_i$ except for the case where $F_I = \{0\} \times \mathbb{R}_{\geq 0}$ because we make no claim for this by the restrictions made in the assertion in the lemma. Note that since F_I contains $(K^\times \times \mathbb{R}) \cap \Gamma_{\geq h}$, the torus orbit corresponding to F_I is contained in the open subset $A \times \mathbb{C}^*$ of \bar{Y} , so the statement follows from the smoothness of A in codimension one. \square

Note that we also have a sequence of log spaces

$$(\bar{X}, \mathcal{M}_{\bar{X}}) \xrightarrow{g^{\bar{X}}} (\bar{X}, \mathcal{F}_{\bar{X}}) \xrightarrow{\bar{t}^\dagger} (\mathbb{A}^1, \mathcal{M}_{\mathbb{A}^1})$$

where we abuse notation by denoting the second map as \bar{t}^\dagger again. Again, we know that the composition $g^{\bar{X}} \circ \bar{t}^\dagger$ is log smooth by Lemma 4.9. When A is singular, note that \bar{X} is disjoint from the torus orbit in \bar{Y} corresponding to $(0 \times \mathbb{R}) \cap \bar{\Gamma}$, so using Assumptions 5.3(4), we conclude the following.

Lemma 5.14. *The map $\bar{t}^\dagger : (\bar{X}, \mathcal{F}_{\bar{X}}) \rightarrow (\mathbb{A}^1, \mathcal{M}_{\mathbb{A}^1})$ is relatively log smooth.*

5.6. The Kato Nakayama space is a fiber bundle. By Rem. 4.13, we may construct the Kato-Nakayama space for $(\bar{Y}, \mathcal{F}_{\bar{Y}})$ and $(\bar{X}, \mathcal{F}_{\bar{X}})$ and by functoriality, we have maps

$$\bar{Y}(\mathcal{M}_{\bar{Y}})_{\log} \xrightarrow{g_{\log}^{\bar{Y}}} \bar{Y}(\mathcal{F}_{\bar{Y}})_{\log} \xrightarrow{\bar{t}_{\log}^\dagger} \mathbb{A}_{\log}^1,$$

$$\bar{X}(\mathcal{M}_{\bar{X}})_{\log} \xrightarrow{g_{\log}^{\bar{X}}} \bar{X}(\mathcal{F}_{\bar{X}})_{\log} \xrightarrow{\bar{t}_{\log}^\dagger} \mathbb{A}_{\log}^1.$$

The statement of Thm. 4.27 in [NO10] allows for the weaker assumption of relative coherency of the source and relatively smoothness of the map, so we conclude from Lemma 5.14 along the same lines as in Section 4.5 the following result.

Theorem 5.15. *The maps of Kato-Nakayama spaces*

$$\begin{aligned} \bar{X}(\mathcal{F}_{\bar{X}})_{\log} &\xrightarrow{\bar{t}_{\log}^\dagger} \mathbb{A}_{\log}^1, \\ \bar{X}(\mathcal{M}_{\bar{X}})_{\log} &\xrightarrow{\bar{t}_{\log}^\dagger \circ g_{\log}^{\bar{X}}} \mathbb{A}_{\log}^1 \end{aligned}$$

are topological fiber bundles.

Moreover, the statement of Prop. 4.28 holds word for word when replacing \bar{X}_{\log} and X_{\log} respectively by $\bar{X}(\mathcal{F}_{\bar{X}})_{\log}$ and $X(\mathcal{F}_X)_{\log}$ where \mathcal{F}_X is the restriction of $\mathcal{F}_{\bar{X}}$ to X .

5.7. Embedding the skeleton $S_{\Delta, \mathcal{T}, K}$ in the Kato-Nakayama space $(\overline{X}(\mathcal{F}_{\overline{X}})_{\log})_1$. We use the following notation for the induced maps on Kato-Nakayama spaces

$$\begin{array}{ccc} \overline{Y}(\mathcal{M}_{\overline{Y}})_{\log} & \xrightarrow{g_{\log}^{\overline{Y}}} & \overline{Y}(\mathcal{F}_{\overline{Y}})_{\log} \\ & \searrow \rho(\mathcal{M}_{\overline{Y}}) & \downarrow \rho(\mathcal{F}_{\overline{Y}}) \\ & & \overline{Y}. \end{array}$$

Proposition 5.16. *Given a point $y \in \overline{Y}$ contained in the torus orbit associated to the face $F \subseteq \overline{\Gamma}$, the map $g_{\log}|_{\rho(\mathcal{M}_{\overline{Y}})^{-1}(y)} : \rho(\mathcal{M}_{\overline{Y}})^{-1}(y) \rightarrow \rho(\mathcal{F}_{\overline{Y}})^{-1}(y)$ is the restriction map*

$$\mathrm{Hom} \left(\frac{\widetilde{M} \cap \mathbb{R}_{\geq 0}(\overline{\Gamma} - G)}{\widetilde{M} \cap \mathbb{R}(G - G)}, S^1 \right) \rightarrow \mathrm{Hom} \left(\frac{\widetilde{M} \cap \mathbb{R}_{\geq 0}(F_G - G)}{\widetilde{M} \cap \mathbb{R}(G - G)}, S^1 \right)$$

induced by the injection $\frac{\widetilde{M} \cap \mathbb{R}_{\geq 0}(F_G - G)}{\widetilde{M} \cap \mathbb{R}(G - G)} \hookrightarrow \frac{\widetilde{M} \cap \mathbb{R}_{\geq 0}(\overline{\Gamma} - G)}{\widetilde{M} \cap \mathbb{R}(G - G)}$.

Proof. This is a straight-forward combination of Def. 4.12 and Lemma 5.10 with the additional observation that $(\mathbb{R}_{\geq 0}(\overline{\Gamma} - G))^{\times} = (\mathbb{R}_{\geq 0}(F_G - G))^{\times} = \mathbb{R}(G - G)$. \square

As before, we denote by $(\overline{X}(\mathcal{F}_{\overline{X}})_{\log})_1$ the fiber of $g_{\log}^{\overline{X}}$ over $(0, 1) \in \mathbb{R}_{\geq 0} \times S^1 = \mathbb{A}_{\log}^1$. There is a surjection

$$g_{\log}^{\overline{X}} : \overline{X}(\mathcal{M}_{\overline{X}})_{\log, 1} \rightarrow \overline{X}(\mathcal{F}_{\overline{X}})_{\log, 1}.$$

Theorem 5.17. *We have a canonical embedding of $S_{\Delta, \mathcal{T}}$ in $\overline{X}(\mathcal{M}_{\overline{X}})_{\log, 1}$ whose image under $g_{\log}^{\overline{X}}$ is canonically identified with $S_{\Delta, \mathcal{T}, K}$.*

Proof. We have the result of Theorem 4.23 already, so in particular an embedding of $\widehat{\partial \Delta}'$ in \overline{X} and of $S_{\Delta, \mathcal{T}}$ in $(\overline{X}(\mathcal{M}_{\overline{X}})_{\log})_1$. We need to show that the image of $S_{\Delta, \mathcal{T}}$ under $g_{\log}^{\overline{X}}$ yields the quotient space $S_{\Delta, \mathcal{T}, K}$. We fix a point $x \in \overline{X}$ in a torus orbit $O_F = \mathrm{Spec} \mathbb{C}[\mathbb{R}(F - F) \cap \widetilde{M}]$ with $F \subseteq \overline{\Gamma}$. Let us regard the composition

$$\overline{X}(\mathcal{M}_{\overline{X}})_{\log, 1} \xrightarrow{g_{\log}^{\overline{X}}} \overline{X}(\mathcal{F}_{\overline{X}})_{\log, 1} \xrightarrow{\rho(\mathcal{F}_{\overline{X}})} \overline{X}.$$

By the Cartesian property of the Kato-Nakayama space in Lemma 4.18, we may use Prop. 5.16 to identify the restriction of $g_{\log}^{\overline{X}}$ to the inverse images of x as the map $T_1 \rightarrow T_2$ where

$$\begin{aligned} T_1 &= \left\{ \alpha \in \mathrm{Hom} \left(\frac{\widetilde{M} \cap \mathbb{R}_{\geq 0}(\overline{\Gamma} - G)}{\widetilde{M} \cap \mathbb{R}(G - G)}, S^1 \right) \mid \alpha(0, 1) = 1 \right\}, \\ T_2 &= \left\{ \alpha \in \mathrm{Hom} \left(\frac{\widetilde{M} \cap \mathbb{R}_{\geq 0}(F_G - G)}{\widetilde{M} \cap \mathbb{R}(G - G)}, S^1 \right) \mid \alpha(0, 1) = 1 \right\}. \end{aligned}$$

Let $p : \widetilde{M}_{\mathbb{R}} \rightarrow M_{\mathbb{R}}$ denote the natural projection and $K_{p(G)}$ denote the smallest face of K containing $p(G)$. We have $p(\overline{\Gamma}) = \Delta$. We use the fact that the condition $\alpha(0, 1) = 1$ in T_1, T_2 can be replaced by changing the source of α to a subquotient of M instead of \widetilde{M} . Precisely,

$$T_1 = \mathrm{Hom} \left(\frac{M \cap \mathbb{R}_{\geq 0}(\Delta - p(G))}{M \cap p(\mathbb{R}(G - G))}, S^1 \right),$$

$$T_2 = \text{Hom} \left(\frac{M \cap \mathbb{R}_{\geq 0}(p(F_G) - p(G))}{M \cap p(\mathbb{R}(G - G))}, S^1 \right).$$

Note that if $x \in \widehat{\partial\Delta'}$ then $K_{p(G)}$ coincides with K_x . Moreover, F_G contains $(K^\times \times \mathbb{R}) \cap \bar{\Gamma}$ and thus corresponds to the face $(F_G + K^\times \times \mathbb{R}) \cap M_{\mathbb{R}}$ of K by Lemma 5.7. We claim that this face is K_G . Indeed by Lemma 5.9 F_G is the smallest face of $\bar{\Gamma}$ containing G and $\bar{\Gamma} \cap K^\times \times \mathbb{R}$ which maps to $K_{p(G)}$ under the bijection in Lemma 5.7. Finally, we may assume that G contains $\bar{\Gamma} \cap K^\times \times \mathbb{R}$ because otherwise $F_G = \bar{\Gamma}$ and $K_G = K$ and this case is clear. We can then identify

$$T_2 = \text{Hom} \left(\frac{M \cap K_G}{M \cap K_G^\times}, S^1 \right)$$

which gives the desired quotient representation of $g_{\log}^{\bar{X}}(\rho(\mathcal{M}_{\bar{X}})^{-1}(x))$ as in Def. 5.6. \square

5.8. Retraction.

Theorem 5.18 (Main Theorem for General Cones). *The skeleton $S_{\Delta, \mathcal{T}, K}$ embeds in Z as a strong deformation retract.*

Proof. By Thm 5.17, we have an embedding $j : S_{\Delta, \mathcal{T}, K} \hookrightarrow (\bar{X}(\mathcal{F}_{\bar{X}})_{\log})_1$ and by Thm 5.15 a homeomorphism $Z \cong (\bar{X}_{\log})_1$. It remains to show that j is a strong deformation retraction. This works word by word the same way in the reasoning that led to Thm 4.26. The point is, that, from the proof of Theorem 5.17 above, we have an explicit description of the fibers of the map $g_{\log}^{\bar{X}}$ over a point $x \in \partial\Delta'$. This allows us to use Lemma 3.24 to lift retractions and construct an iterative argument exactly as in Theorem 4.26. \square

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